

VISUAL OBJECT RECOGNITION

STATE-OF-THE-ART
TECHNIQUES AND
PERFORMANCE EVALUATION

LECTURE 1: INTRODUCTION

- ✻ **Visual Object Recognition**
what's the problem?
- ✻ **Terminology and Taxonomy**
Classification, Categorisation, Detection, Pose estimation, Articulation, Expression.
- ✻ **About this course**
lecture format, projects, exam

VISUAL OBJECT RECOGNITION

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- ✱ For evolutionary reasons...



VISUAL OBJECT RECOGNITION

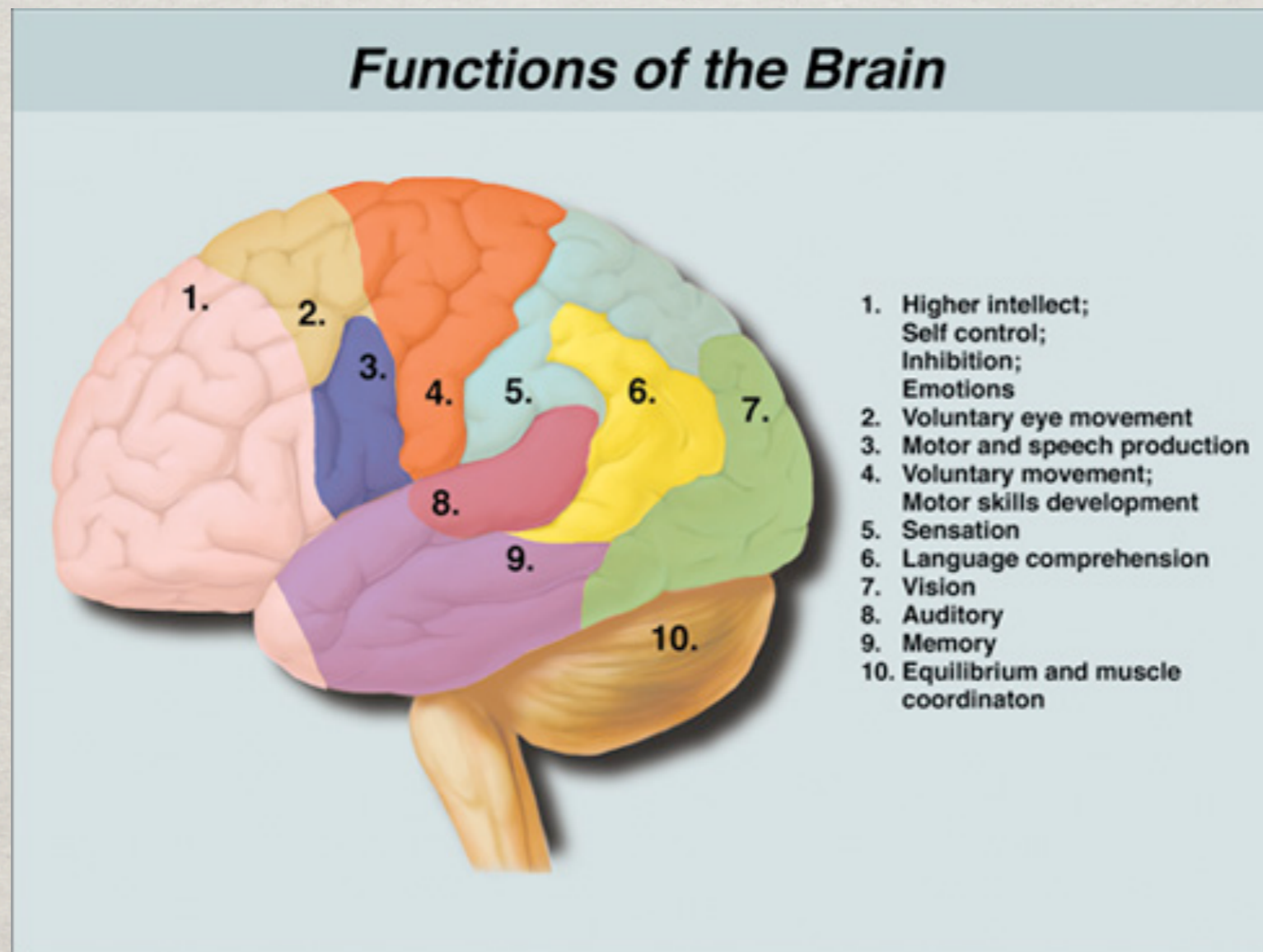
- ✱ OR happens very quickly in the human visual system. Bottom up process takes less than 150ms (S. Thorpe et al. 1996).
- ✱ For evolutionary reasons.
- ✱ Since it is a pre-conscious process in our brains, we do not intuitively think of object recognition as being difficult.

MORAVEC'S PARADOX

- ✱ Initially in AI computer vision was assumed to be simple, and logical inference hard.
- ✱ “Just detect the objects in an image and generate the appropriate symbols”
- ✱ Only symbolic reasoning and and inference was seen as proper AI problems.
- ✱ Now we know that computer vision is much more complex than logical inference.

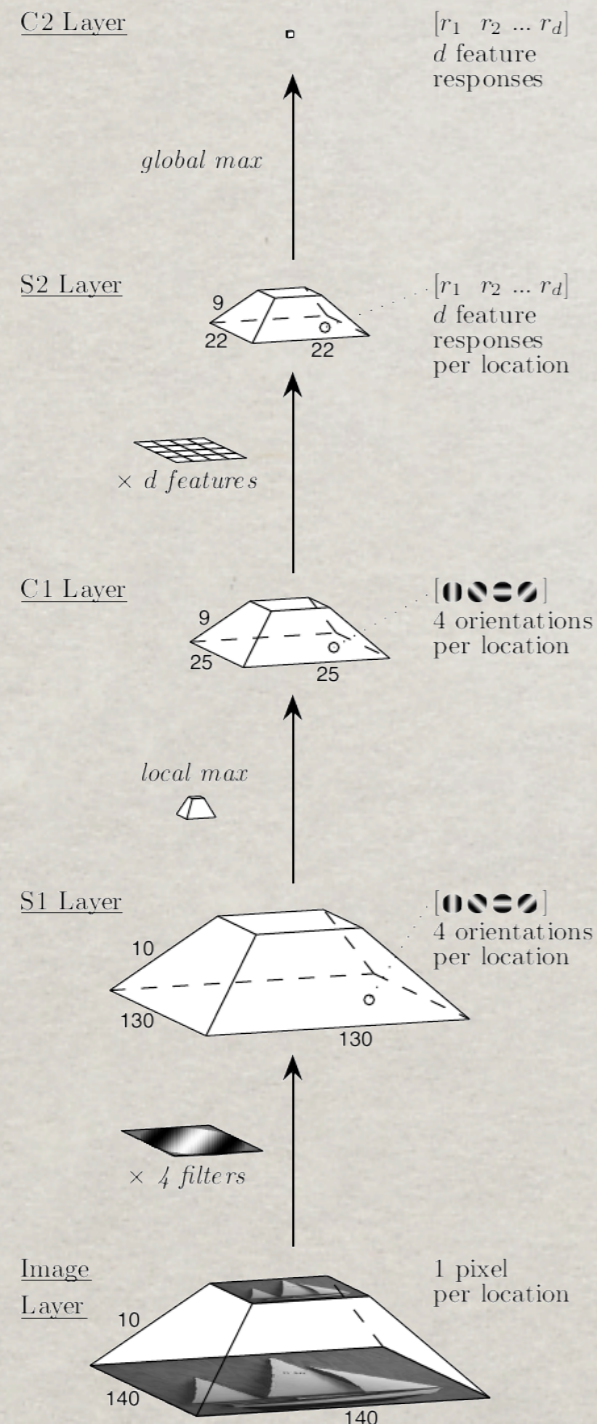
VISUAL OBJECT RECOGNITION

☼ von Neumann vs. Brain architectures



www.braininjurylegalguide.com

VISUAL OBJECT RECOGNITION



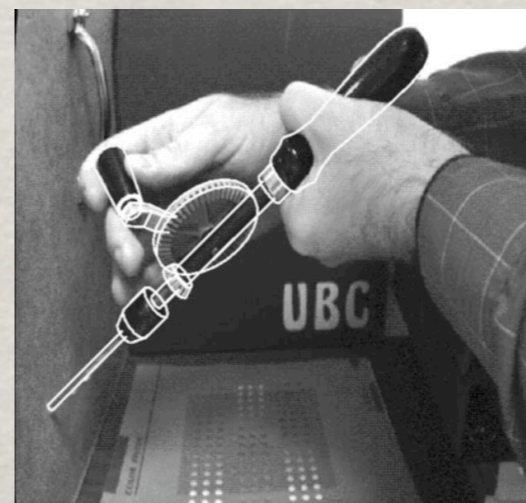
- ✱ The “Standard Model”, Riesenhuber & Poggio, *Nature Neuroscience* vol.2 no.11, 1999
- ✱ Alternating *template matching* and *local max* operations.
- ✱ Decreasing spatial resolution, increasing number of feature types
- ✱ Perception only, no motor functions (head & eye movements)

WHAT DO WE MEAN BY VISUAL RECOGNITION?

- ✱ The same **object instance**?
- ✱ The same **class? category**?
- ✱ The same **pose**?
- ✱ The same **articulation? expression**?



Johansson&Moe CRV05

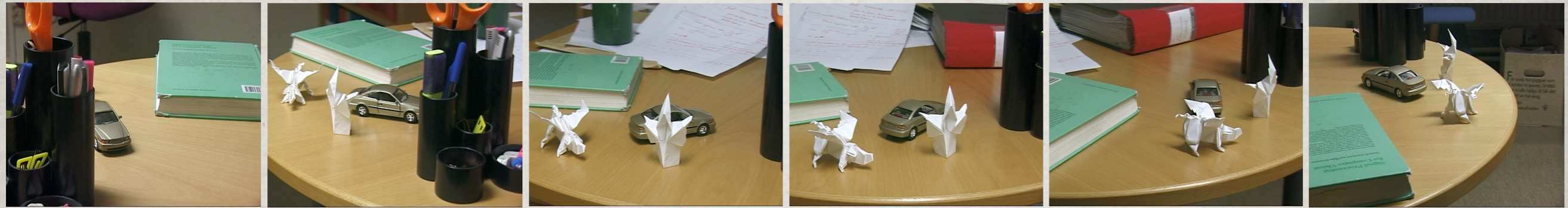


Lowe PAMI91



www.cwu.edu/~warren/

OBJECT INSTANCE RECOGNITION



Johansson&Moe CRV05

- ✱ Recognition of **the same object**
 - ✱ Different view/pose (also pose estimation)
 - ✱ Different illumination
 - ✱ The same articulation/expression

OBJECT INSTANCE RECOGNITION

- ✱ Application: Pose estimation for bin picking
 - ✱ Several identical instances of the object need to be distinguished

Random Bin Picking



<http://www.braintech.com/videos-rbp.php>

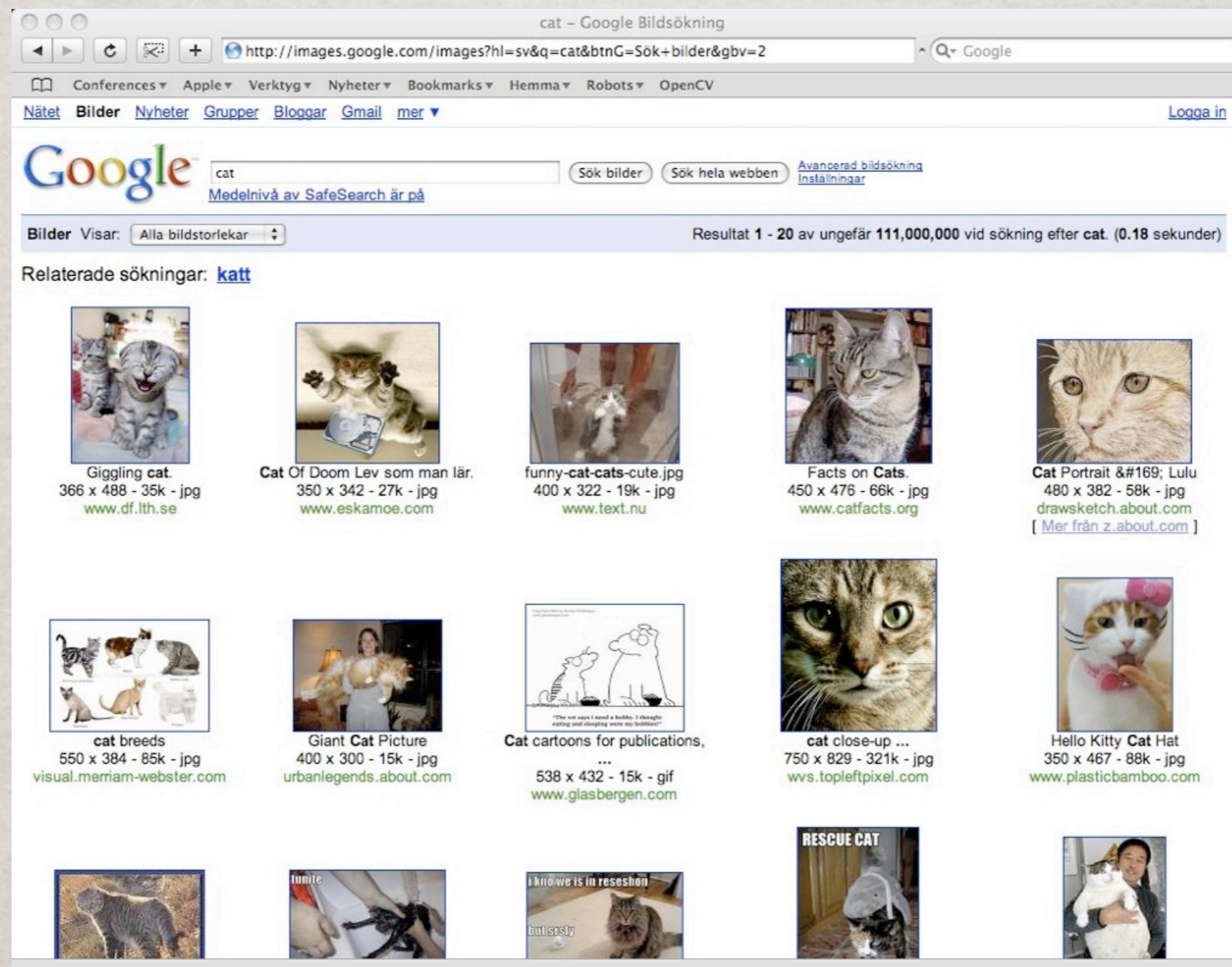
OBJECT CLASS RECOGNITION



- ✱ Recognition of an **object class/category**
- ✱ Different instance
- ✱ Different view/pose
- ✱ Different illumination
- ✱ Different articulation/expression

OBJECT CLASS RECOGNITION

☼ Main application is image database search:



OBJECT CLASS RECOGNITION

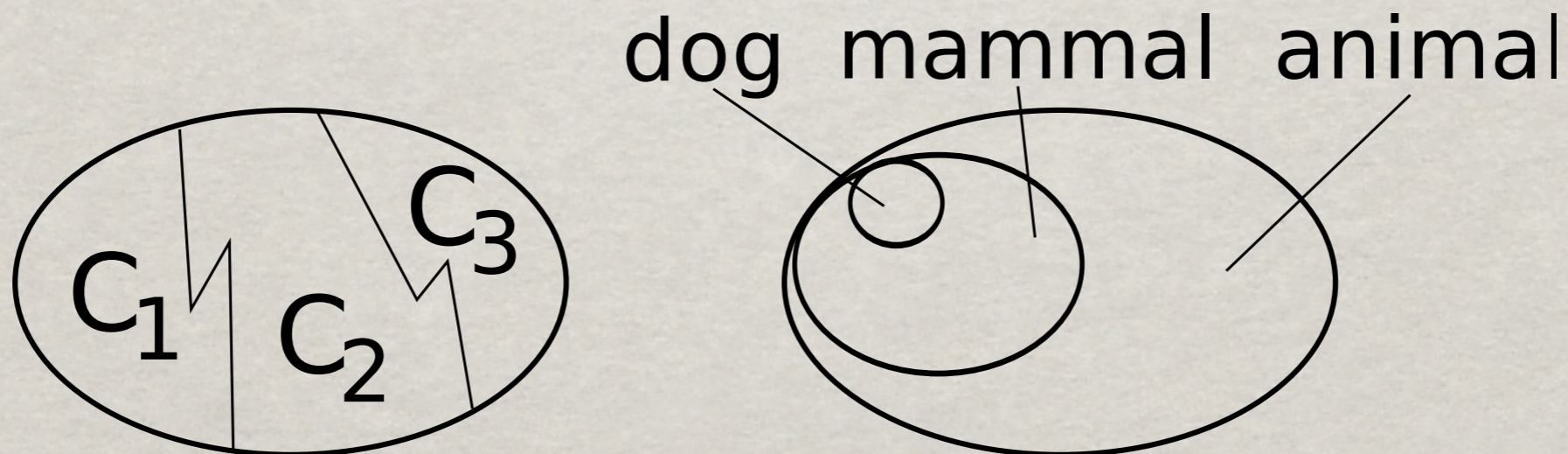
✻ Other application “semantic robot vision”:



<http://www.semantic-robot-vision-challenge.org/>

CLASSES AND CATEGORIES

- ✱ Object class is a computer science construct
- ✱ Implicit assumption: It is possible to partition a dataset into disjoint classes
- ✱ This fits poorly to the structure of natural language where categories are often nested hierarchically, e.g.



CLASSES AND CATEGORIES

- ✱ Natural categories tend **not** to be defined by appearance alone.

- ✱ Applicable actions also matter

e.g. a “chair” is something you sit on. Number of legs, colour etc. does not matter.



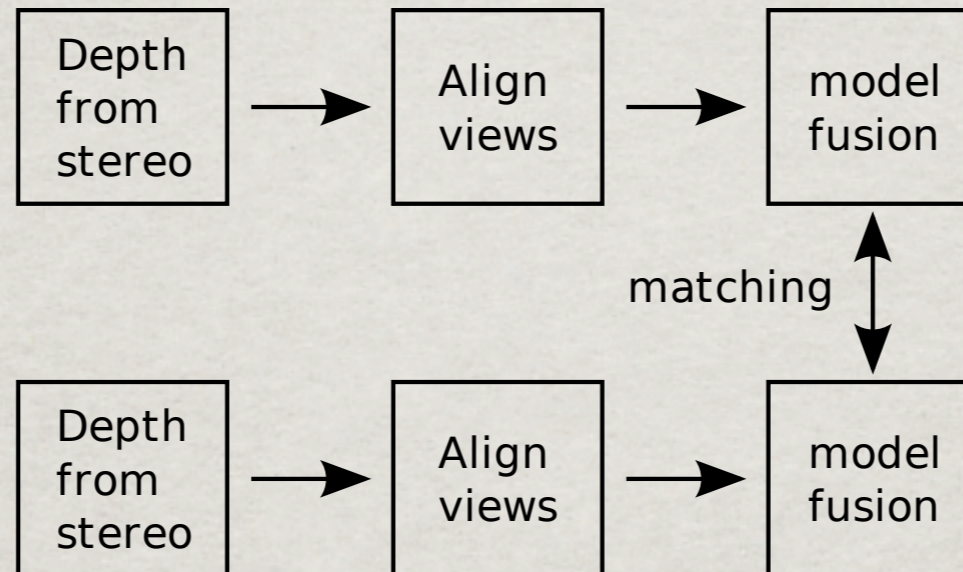
CLASSES AND CATEGORIES

- ✻ A category member is instead recognized as being similar to one of **possibly several prototypical** category members.
- ✻ Category membership is not a binary decision.
- ✻ Lakoff, George, “*Women, Fire, and Dangerous Things - what categories reveal about the mind*”. University of Chicago Press. 1987

TAXONOMY OF RECOGNITION APPROACHES

- ✱ **Full 3D modelling+recognition** (old school)
- ✱ **Appearance based methods:**
 - ✱ **Global appearance** (pattern matching)
 - ✱ Good for e.g. silhouettes and faces
 - ✱ **Local feature methods**
 - ✱ can handle **occlusion** and **articulation**
 - ✱ make 3D models **after** recognition

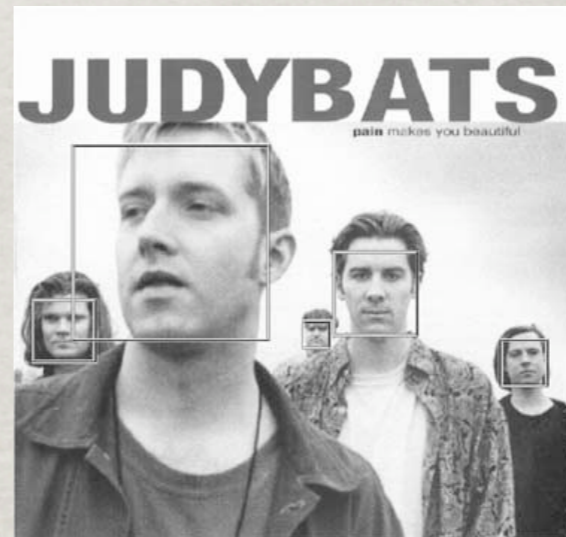
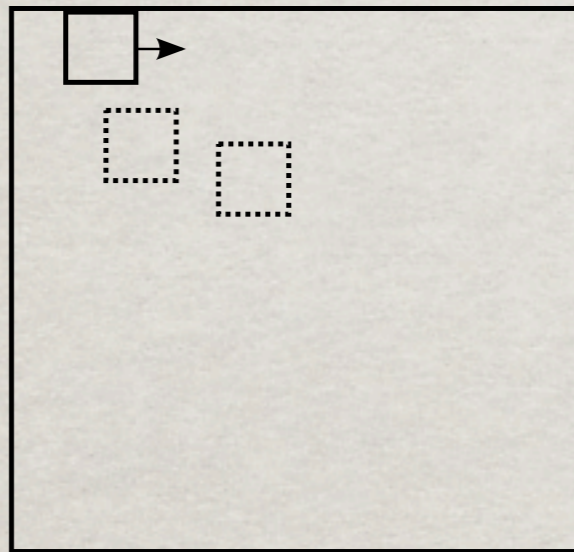
FULL 3D MODELLING



- ✱ First generate a 3D model, then match the 3D model to memory
- ✱ Bad as it adds new error sources.
- ✱ “The world is it’s own best model”, R. Brooks
“Elephants don’t play chess”, RAS 6, 1990

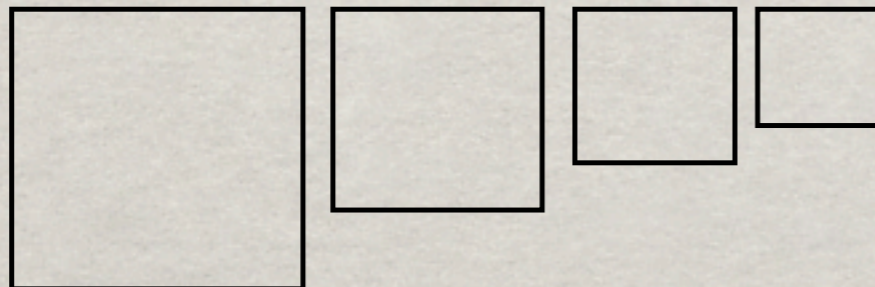
GLOBAL APPEARANCE

- ✿ Run a fast pattern recognition algorithm as a sliding window detector.



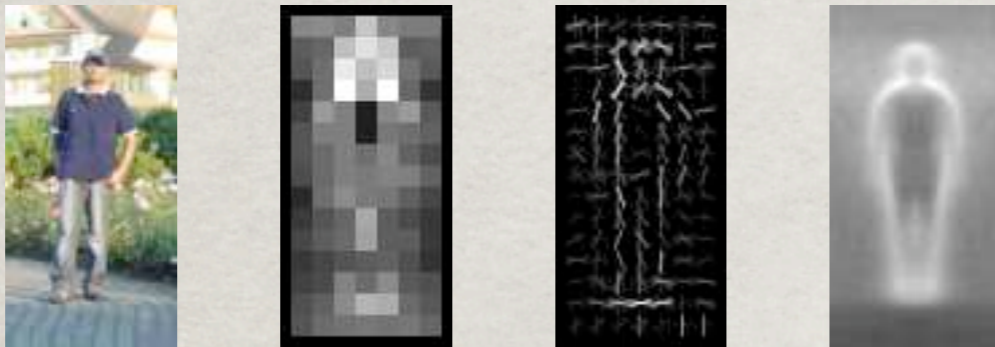
Viola&Jones IJCV04

Scale pyramid for scale invariance



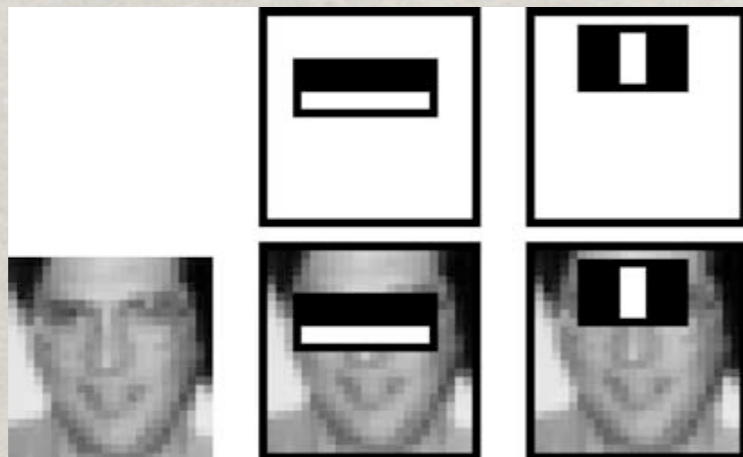
GLOBAL APPEARANCE

☼ Pedestrian detection

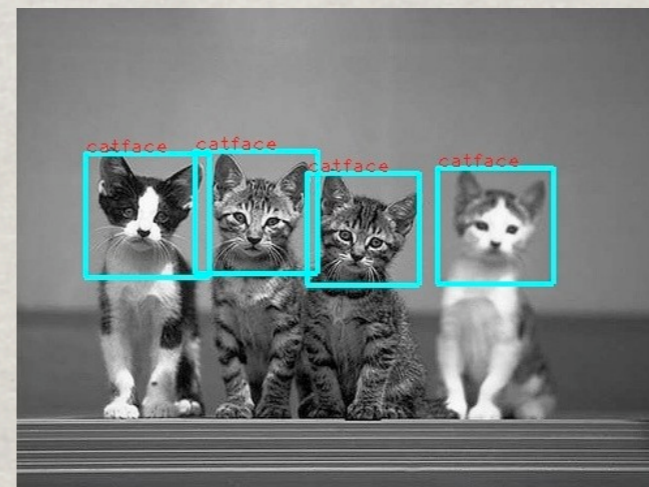


Dalal&Triggs, CVPR'05

☼ Cascaded face detection



Viola&Jones IJCV'04



Ivan Laptev

GLOBAL APPEARANCE

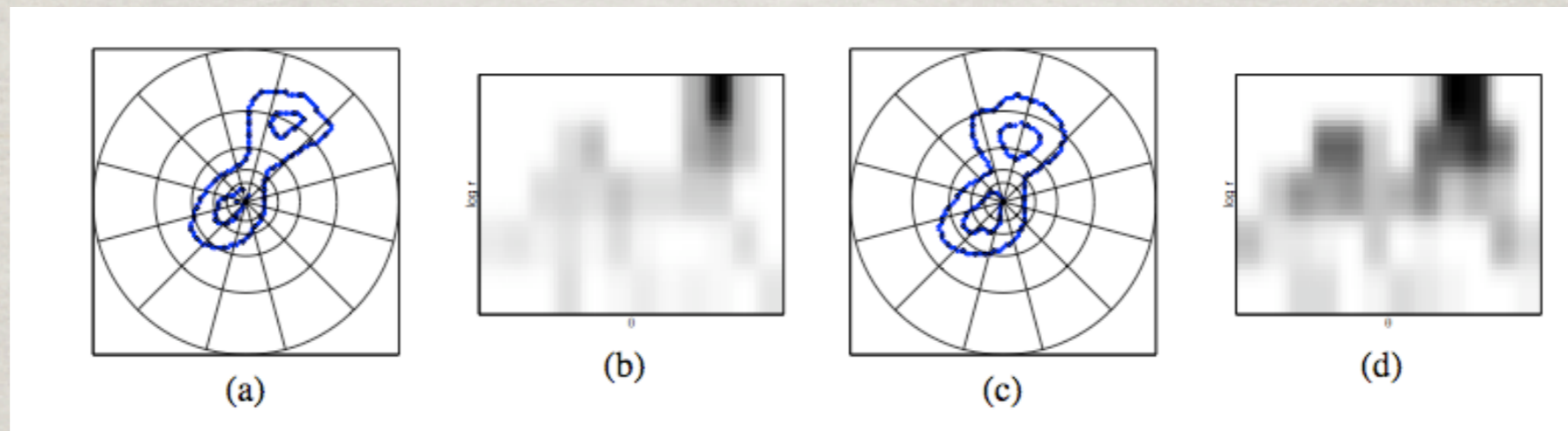
- ✿ Application: Cascaded face detection for autofocus



www.adorama.com review of Fujifilm finepics F40fd

GLOBAL APPEARANCE

- Global Elastic Contour models



e.g. Zhang & Malik, CVPR2003

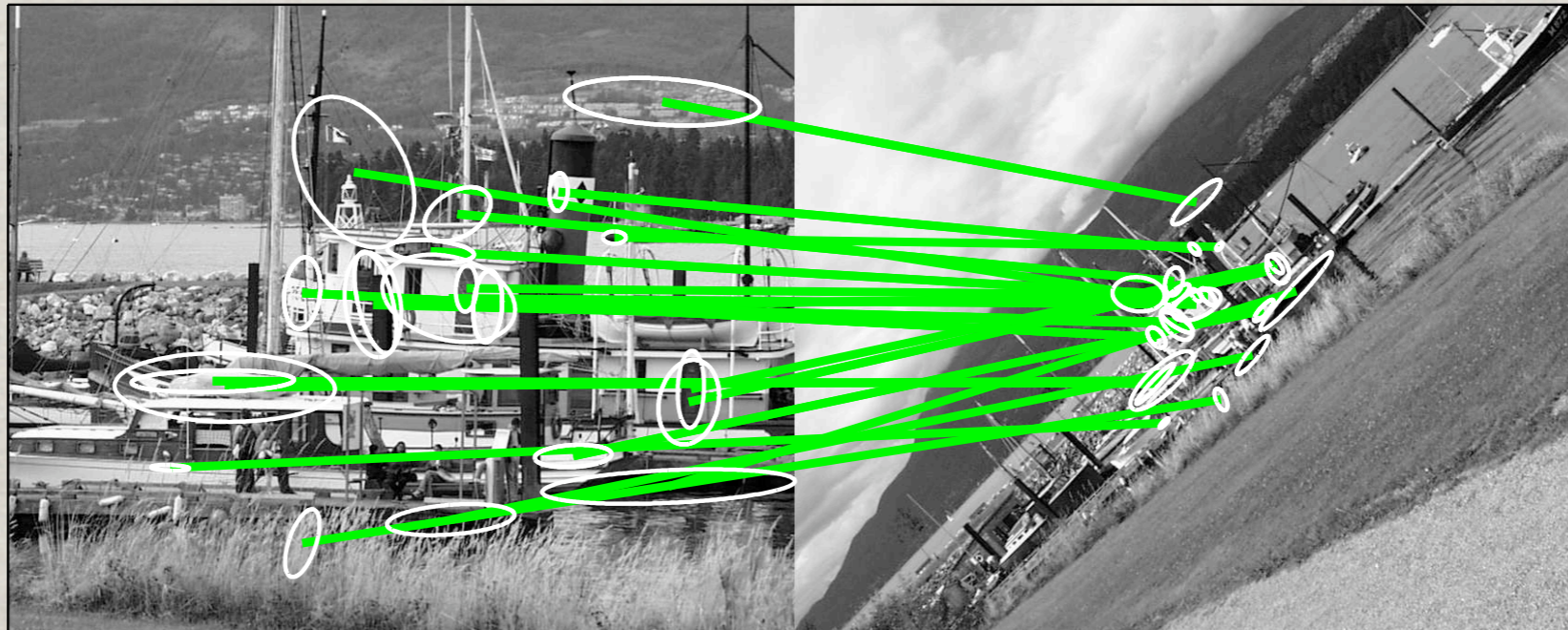
- Useful for e.g., human and animal silhouettes and hand drawn symbols.

GLOBAL APPEARANCE

- ✱ Good for non-articulate objects and objects with small articulation.
- ✱ Pose can be dealt with by running one detector for each pose.
E.g. for faces: frontal, left side, right side.
- ✱ Handles lower resolution than local appearance models.
- ✱ Occlusion is problematic.
- ✱ Large training data sets are needed.

LOCAL APPEARANCE MODELS

- ✱ Detect local invariant frames and cut out many patches.
- ✱ Try to match all patches in image to all patches in memory.



Forssén, Lowe ICCV07

LOCAL APPEARANCE MODELS

- ✻ Can handle occlusion
- ✻ Deals with rotations, scale changes, and affine distortions.
- ✻ Can handle large view changes, 25-60deg, depending on what is imaged
- ✻ Requires higher resolution than sliding window approach
- ✻ The focus of this course.

LOCAL APPEARANCE MODELS

- ✱ Lecture 2: Image formation and invariances
- ✱ Lecture 3: Detection of canonical frames
- ✱ Lecture 4: Descriptor construction
- ✱ Lecture 5: Metrics for comparison
- ✱ Lecture 6: Tree search and hashing
- ✱ Lecture 7: Performance evaluation

COURSE FORMAT

☼ Two options

- ☼ If you are not a doctoral student you may skip the project, and just follow the lectures. You should still read the papers of course.
- ☼ PhD students should also do the project, and the final exam.

COURSE FORMAT

☼ The Lectures

- ☼ Each lecture has an associated paper, chosen both for content and readability.
- ☼ The paper should be read in advance
- ☼ PDFs of papers are available on the course web page:

<http://www.cvl.isy.liu.se/Education/Graduate/VOR/articles/>

COURSE FORMAT

- ✻ **The Lectures, preparation**
 - ✻ Read the paper thoroughly
 - ✻ Make notes of related questions and issues you want to discuss
 - ✻ Each participant should prepare at least two issues/questions for each lecture

COURSE FORMAT

☼ The Project

- ☼ For 8hp you are also expected to do a small programming project
- ☼ You are encouraged to suggest your own project.
- ☼ A list of possible other project topics will be handed out later.
- ☼ Duration should be approx 2 weeks including the writing of a small report.

COURSE FORMAT

☼ The Exam

- ☼ The course will end with a written exam
- ☼ If 4 people or fewer, possibly an oral exam
- ☼ Be prepared to answer questions about concepts and algorithms introduced in the course.