# Supplementary Material

## Beyond Correlation Filters: Learning Continuous Convolution Operators for Visual Tracking

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In this supplementary material of [6] we provide additional derivations and implementation details. Section 1 provides details about the derivation of eq. (5) in the paper. Section 2 contains detailed derivations of the Fourier coefficients of the desired convolution output  $y_j$  and the interpolation functions  $b_d$ , described in section 3.4 in the paper. Details about the numerical optimization is given in section 3. We provide detailed results on the OTB-2015 and Temple-Color datasets in sections 4 and 5 respectively. In our object tracking experiments, we use the same parameter settings for our method in all state-of-the-art comparisons (sections 5.2, 5.3 and 5.4), i.e. for all datasets and videos. Further, we use the same parameter settings for all feature point tracking experiments. Code, raw result files and a video of qualitative feature point tracking results on the MPI Sintel dataset are available at the project webpage http://www.cvl.isy.liu.se/research/objrec/visualtracking/conttrack/index.html.

## 1 Fourier Coefficients of the Interpolated Feature Map

We first derive the expression for the Fourier coefficients of the interpolated feature map  $J_d\{x^d\}$ , which is used to prove eq. (5) in the paper. The interpolation operator  $J_d: \mathbb{R}^{N_d} \to L^2(T)$  for feature channel d is defined as (same as eq. (2) in the paper),

$$J_d\{x^d\}(t) = \sum_{n=0}^{N_d-1} x^d[n] b_d \left(t - \frac{T}{N_d} n\right). \tag{1}$$

Here,  $b_d \in L^2(T)$  is the interpolation function for channel d. From the shift property [21], it follows that  $b_d \left(t - \frac{T}{N_d} n\right)$  has Fourier coefficients  $\exp\left(-i\frac{2\pi}{N_d}k\right)\hat{b}_d[k]$ . By utilizing linearity, the Fourier coefficients of (1) are then derived as,

$$\widehat{J_d\{x^d\}}[k] = \sum_{n=0}^{N_d-1} x^d[n] e^{-i\frac{2\pi}{N_d}k} \hat{b}_d[k] = \hat{b}_d[k] \sum_{n=0}^{N_d-1} x^d[n] e^{-i\frac{2\pi}{N_d}k} = \hat{b}_d[k] X^d[k].$$
 (2)

Here,  $X^d[k] := \sum_{n=0}^{N_d-1} x^d[n] e^{-i\frac{2\pi}{N_d}nk}$ ,  $k \in \mathbb{Z}$  is the periodically extended discrete Fourier transform (DFT) of  $x^d$ . The Fourier coefficients of the confidence output (eq. (5) in the paper) are then derived from (2) here and eq. (1) in the paper by exploiting linearity and the first convolution property [21] (see section 3.1 in the paper) of the Fourier coefficients.

# 2 Fourier Coefficients of $y_j$ and $b_d$

We construct the desired convolution output  $y_j$  and interpolation function  $b_d$  as periodic repetitions of functions defined on the real line. For an integrable function  $g \in L^1(\mathbb{R})$ , we define the T-periodic repetition (or periodic summation) as  $g_T(t) = \sum_{n=-\infty}^{\infty} g(t-nT)$ . The Fourier coefficients  $\hat{g}_T[k]$  of  $g_T$  can then be obtained by evaluating the Fourier transform  $\hat{g}(\xi) = \int_{-\infty}^{\infty} g(t)e^{-i2\pi\xi t} \,\mathrm{d}t$  of g at discrete locations using Poisson summation formula [21],

$$\hat{g}_T[k] = \frac{1}{T}\hat{g}\left(\frac{k}{T}\right). \tag{3}$$

In the proposed learning framework,  $y_j \in L^2(T)$  is the desired output of  $S_f\{x_j\}$ , i.e. the convolution operator applied to the sample  $x_j$ . Thus, in our formulation, the training sample  $x_j$  is labeled by an entire confidence function (or heat-map)  $y_j$  of the target presence at all continuous locations. The function value  $y_j(t)$  represents the labeled confidence score at the location  $t \in [0,T)$ . As  $y_j \in L^2(T)$  is arbitrary, it can be tailored for the specific application. For the visual tracking, a suitable approach is to construct  $y_j$  based on a Gaussian function. We let  $y_j(t) = \sum_{n=-\infty}^{\infty} z_j(t-nT)$  be the periodic repetition of the Gaussian function,

$$z_j(t) = e^{-\frac{1}{2\sigma^2}(t - u_j)^2} \,. \tag{4}$$

Here,  $u_j \in [0, T)$  is the estimated location of the target (or feature point) in the corresponding sample  $x_j$  and  $\sigma$  is a parameter. The Fourier transform of (4) is derived as  $\hat{z}_j(\xi) = \sqrt{2\pi\sigma^2} \exp\left(-i2\pi u_j\xi\right) \exp\left(-2\sigma^2\left(\pi\xi\right)^2\right)$  using the transform pair of a Gaussian function and the shift property (see e.g. [21]). The Fourier coefficients are thus computed using (3) as,

$$\hat{y}_j[k] = \frac{1}{T}\hat{z}_j\left(\frac{k}{T}\right) = \frac{\sqrt{2\pi\sigma^2}}{T}\exp\left(-2\sigma^2\left(\frac{\pi k}{T}\right)^2 - i\frac{2\pi}{T}u_jk\right). \tag{5}$$

The interpolation functions  $b_d$ , used in the interpolation operator (1), are constructed using the standard cubic spline kernel [24],

$$b(t) = \begin{cases} (a+2)|t|^3 - (a+3)t^2 + 1 & |t| \le 1\\ a|t|^3 - 5at^2 + 8a|t| - 4a & 1 < |t| \le 2\\ 0 & |t| > 2 \end{cases}$$
 (6)

In our experiments, we use the value a=-0.75 for the shape parameter. The interpolation function for channel d is obtained by first rescaling b to the sample interval  $T/N_d$ . It is then shifted half an interval  $T/(2N_d)$  to align the origin of the continuous coordinate system with the sampling intervals of the feature map. The resulting interpolation kernel  $c_d$  and its Fourier transform are given by,

 $c_d(t) = b\left(\frac{N_d}{T}\left(t - \frac{T}{2N_d}\right)\right) , \quad \hat{c}_d(\xi) = \frac{T}{N_d}e^{-i\pi\frac{T}{N_d}\xi}\hat{b}\left(\frac{T}{N_d}\xi\right)$  (7)

Here,  $\hat{c}_d$  is obtained through the shift and scaling property of the Fourier transform. The analytical expression for the Fourier transform of (6) is given by,

$$\hat{b}(\xi) = \frac{6(1 - \cos 2\pi \xi) + 3a(1 - \cos 4\pi \xi) - (6 + 8a)\pi \xi \sin 2\pi \xi - 2a\pi \xi \sin 4\pi \xi}{4\xi^4 \pi^4}.$$
(8)

The Fourier coefficients of  $b_d(t) = \sum_{-\infty}^{\infty} c_d(t - nT)$  are obtained through (3) as,

$$\hat{b}_d[k] = \frac{1}{T}\hat{c}_d\left(\frac{k}{T}\right) = \frac{1}{N_d}\exp\left(-i\frac{\pi}{N_d}k\right)\hat{b}\left(\frac{k}{N_d}\right). \tag{9}$$

### 3 Conjugate Gradient Optimization

For the target tracking application we employ the Conjugate Gradient (CG) method [20] to iteratively optimize the filter coefficients  $\hat{\mathbf{f}}$  by solving the normal equations (e.q. (8) in the paper),

$$(A^{\mathrm{H}}\Gamma A + W^{\mathrm{H}}W)\,\hat{\mathbf{f}} = A^{\mathrm{H}}\Gamma\hat{\mathbf{y}}\,. (10)$$

Here, the matrix A originates from the data term of the loss (e.q. (7) in the paper) and consists of one diagonal block per feature dimension d and training sample j. The diagonal matrix  $\Gamma$  contains the sample weights  $\alpha_j$ . The matrix W corresponds to a multi-channel convolution operation, where each channel d is convolved with the Fourier coefficients  $\hat{w}$  of the penalty function. The vector  $\hat{y}$  is the concatenation of the Fourier coefficients of all label functions  $y_j$  (see section 3.3 in the paper for more details).

We perform 100 CG-iterations in the first frame to converge to a good initial estimate of the filter  $\hat{\mathbf{f}}$ . In the subsequent frames, we use 5 iterations per frame and initialize CG with the current filter (as computed in the previous frame). To further speed up the convergence, we initialize the previous search direction in CG to a forgetting factor times the final conjugate direction used in the previous frame. This forgetting factor is set to  $(1-\lambda)^{10}$ , where  $\lambda$  is the learning rate of the tracker. The CG method is commonly used with a preconditioner to improve the condition number of the matrix and thereby the convergence rate of the solver. We employ an approximate diagonal preconditioner, which is computed as an efficient weighted running average of the training samples.

Our Conjugate Gradient optimization has a number of advantages compared to the Gauss-Seidel approach used in [3,4] regarding complexity and implementation. First, CG does not require explicit evaluations of the matrix product  $A^{\rm H}\Gamma A$ . We therefore obtain a linear  $\mathcal{O}(D)$  instead of quadratic  $\mathcal{O}(D^2)$  complexity of the computations and memory consumption in the number of feature channels D. This is important for high-dimensional deep feature maps, as employed in this work. Secondly, CG can utilize the specific sparsity structure of the problem (10). We exploit that A can be permuted to a block-diagonal structure, containing one (dense) block matrix per Fourier coefficient  $k = -K, \ldots, K$ .

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The operations  $\mathbf{v} \mapsto A\mathbf{v}$  and  $\mathbf{v} \mapsto A^H\mathbf{v}$  in CG is implemented solely using dense block-wise matrix-vector multiplications. We also use the fact that the matrices W and  $W^H$  correspond to convolution operations over all feature channels with the kernel  $\hat{w}$  and its Hermitian adjoint respectively. The operation  $\mathbf{v} \mapsto W^HW\mathbf{v}$  in CG is performed as convolutions and thus W is not constructed explicitly. Since the Fourier coefficients of a real function obey the Hermitian symmetry, we only need to process half the Fourier coefficients  $0 \le k \le K$ . This effectively halves the computations and memory consumption of the training procedure. Finally, as the required operations in (10) are implemented as either block-wise dense matrix-vector multiplications, ordinary convolutions or element wise multiplications, our framework does not require explicit handling of sparse matrices (using e.g. sparse matrix libraries), which simplifies implementation.

### 4 Detailed Results on OTB-2015

In this supplementary material, detailed results on OTB-2015 [25] with 100 videos are provided. Videos and ground truth are available at <a href="https://sites.google.com/site/benchmarkpami/">https://sites.google.com/site/benchmarkpami/</a>. Figure 1 contains the success plots for all 11 attributes and Table 2 shows the per-video overlap precision for all trackers in the comparison.

### 5 Detailed Results on Temple-Color

We also present detailed results on the Temple-Color dataset [17] with 128 videos. Videos and ground truth are available at http://www.dabi.temple.edu/~hbling/data/TColor-128/TColor-128.html. The per-video overlap precision for all trackers in our comparison are reported in table 2.

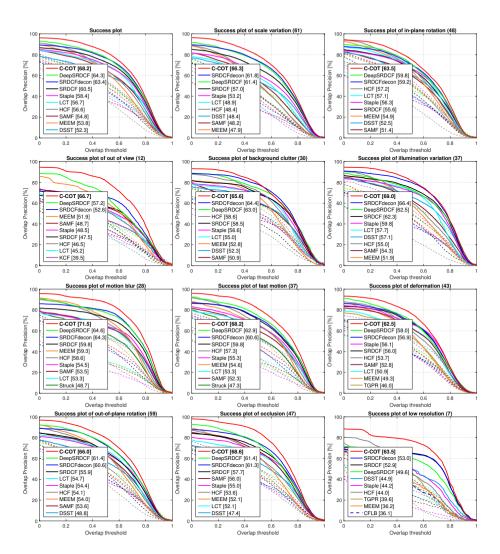


Fig. 1. Success plots on OTB-2015 [25] dataset. The overall success plot (top-left) is computed over the entire dataset (same as in figure 2a in the paper). We also show the success plots for all 11 attributes. The title of each attribute plot contains the name of the attribute and the number of videos associated with it. The area-under-the-curve (AUC) score is shown in the legend. For clarity, we only display the top 10 trackers in the legend. Our object tracking framework achieves the best results on all 11 attributes.

**Table 1.** A per-video comparison on the OTB-2015 dataset [25] with 100 videos. The results are shown in terms of overlap precision (OP) (in percent), which corresponds to the PASCAL criterion. The best and second best results for each video are shown in red and blue font respectively. Our object tracking framework achieves a significant gain of 5.1% in mean OP, compared to the second best tracker (DeepSRDCF).

Video	EDFT	LSHT	DFT	ASLA	TLD	Struck	CFLB	ACT	TGPR	KCF	DSST	SAMF	DAT	MEEM	LCT [10]	HCF	Staple	SRDCF	SRDCFdecon	DeepSRDCF	C-COT
Basketball	[8]	[12] 4.55	71.6	[14]   65.2	31.3	[11] 11	9.1	48.7	91.3	89.8	[2] 69.8	96.7	89.5	[26] 83	99.2	99.9	[1] 87.2	41.2	30.1	28.3	98.9
Biker	26.7	8.89	26.7	46.7	32.6	26.7	48.1	26.7	87.4	26.7	28.1	31.9	44.4	26.7	45.9	25.9	26.7	48.9	46.7	51.9	53.3
Bird1 Bird2	26.7 94.9	4.41 85.9	26.2	2.45	0.49	15.4 52.5	0.98	2.45	31.1 85.9	6.37 46.5	6.62 47.5	5.64 98	30.1	4.41	77.8	19.9	27.7 96	6.37 54.5	5.64 54.5	26.2 84.8	5.64 100
BlurBody	11.7	26	11.4	15	44	98.8	41.3	53.9	98.5	58.7	62.3	95.8	37.1	98.8	99.4	99.1	99.7	100	100	100 99.9	98.8
BlurCar1 BlurCar2	1.48 7.35	1.21 21.9	7.68 17.4	2.29 12.3	13.6 84.8	99.9 93.8	50.4 94.7	69.9 94.7	94.5 93.8	100 94.7	98.8 100	100 99.8	1.48	100 94.7	100	99.7 94.7	69.5 100	99.9 100	99.9 100	99.9 100	99.9 100
BlurCar3	5.6	30.8	11.8	12	93.6	100	56	32.8	93.3	99.4	100	100	25.2	100	100	100	98.9	100	100	100	100
BlurCar4 BlurFace	96.8 24.1	33.7 11.8	100 29	21.8 15	42.6 100	100 44	100 31.4	100 100	99.7	100 100	100 100	100 100	100 26	100	100	100	100 99.8	100 100	100	100 100	100 100
BlurOwl	4.28	9.83	10.8	11.4	63.9	98.6	94.1	20.8	13.6	22.8	22	23.1	99.8	99	89.4	96.5	50.6	98.6	97.1	100	100
Board Bolt	19.4	86.5 32.6	19.9	50.9 1.43	14.1	79.9	68.1	73.7 100	11.3	85.5 94.3	84.2 100	97.1	2.01 96	82.5 88	85.4 98.9	94.7	77.8 99.7	85.7 1.43	95.7 1.43	96.6 74.6	87.2 90.6
Bolt2	0.683	52.9	0.683	0.683	0.683	4.44	34.5	27	0.683	0.683	1.02	0.683	63.5	0.683	0.683	88.4	91.1	1.02	1.02	85.3	65.5
Box	16.4 98	33.7 50.7	30.9 48.3	57.2 43.5	61.6 82.9	58.7 97.5	32.5 98.5	33.6 95	35.8 99	35.7 99.2	39.6 100	92.9	5.86 96.3	83.5 99.2	8.96 100	33.7 99	41.5 100	41.5 100	96 99.7	39.7 99.8	89.5 100
Car1	5.39	5.39	5.39	81.6	38.7	5.39	6.27	5.39	7.75	5.39	60.5	36.3	5.39	5.39	20.8	5.39	76.5	100	100	100	100
Car24	17.3	98.2 17.2	7.19	100	100	100 17	99.7	100 17.3	9.2	100 17.3	100 17.3	100 15.7	7.34	100 17.2	100 85.3	100 17.3	100 17.3	100 100	100 100	100 100	100
Car4	27.5	27.6	25.8	100	24	39.9	25	27.6	40.7	36.4	100	100	0.152	26.4	98.9	39.6	100	100	100	100	100
CarDark CarScale	68.4 44.8	60.6 44.8	33.6 44.8	100 71	53.7 68.7	100 43.3	97.7 44.8	100 44.8	100 40.5	69.2 44.4	100 84.5	58.3 59.9	2.04	100 44.8	99.2 79	88.3 44.4	100	100 84.1	100 85.3	100 81	100 80.2
ClifBar	29.7	28.2	23.9	37.7	42.2	21.6	25.6	31.8	9.32	30.1	88.6	25.6	29.4	60.6	70.3	41.7	58.9	44.1	85	59.1	71.2
Coke Couple	14.4	49.8 9.29	8.59	14.4	57.4	94.2	70.4 63.6	64.3	88 58 6	72.2	83.2	79.7 45.7	47.8 63.6	95.5 75.7	91.4 52.9	91.4	77 67.9	63.6	65.6 92.9	50.5 77.9	54 72.1
Coupon	100	100	100	100	38.8	100	100	100	37.9	100	100	100	99.1	39.4	100	100	100	100	100	100	100
Crossing Crowds	75 91	40 54.3	64.2 91	100 89	45.8	95.8 68.2	98.3 90.8	88.3 96.8	98.3 86.7	95	100 90.2	100	97.5 1.73	98.3 83.8	100 96.2	95 99.4	100	100 95.1	100 89.6	100 90.8	100 97.4
Dancer	89.3	88.4	89.8	100	88.9	68.2 85.8	89.3	90.7	91.6	91.6	100	100	73.8	80.9	96.2 100	99.4 91.6	100	100	100	100	100
Dancer2 David	100 55.4	100 28.2	100 23.4	100 94.9	84 61.1	100 23.6	100 23.8	100 62.6	100 80.5	100 62.2	100 100	100 95.8	98.7 39.1	98.7 62.6	100 92.8	100 60.1	100 96.2	100 98.9	100 97.5	100 100	100
David2	100	100	54.2	83.6	100	100	100	100	100	100	100	100	11	100	100	92.2	100	100	100	100	100
David3 Deer	87.3 63.4	74.6 4.23	74.2	49.6 4.23	32.1	33.7	53.6 100	87.7 100	98.8	99.2 81.7	52.8 78.9	100 88 7	100 9.86	94	98 81.7	100	100 83.1	100 100	96.4	100 100	99.6 100
Diving	18.6	16.7	18.6	17.7	16.7	18.1	18.6	18.6	18.1	18.6	18.1	18.6	18.6	17.2	18.6	18.6	19.1	18.6	18.1	18.6	18.6
Dog Dog1	19.7 64.4	15 54.3	19.7 52.1	66.1	72.4 75.6	15.7 65.2	13.4 58.4	13.4	22.8 66.9	14.2 65.1	60.6 100	47.2 72.8	18.1 6.52	14.2 62.9	33.9 100	13.4 65.2	59.8 100	49.6 100	59.8 100	79.5 100	83.5 100
Doll	49.3	23	35	92.2	69.3	68.9	72.4	49.6	86.4	55.2	99.7	65.2	18.3	72.9	99.4	72.9	99.8	99.7	99.7	90.1	99.7
DragonBaby Dudek	22.1 82.3	19.5 89.9	11.5 80.1	15.9 90.5	13.3 67	8.85 98.1	6.19 95.5	23 96.1	38.1 94.6	30.1 97.6	6.19 98.1	63.7 98.2	39.8 18.1	80.5 95.3	31 99.9	78.8 97.6	58.4 67.3	30.1 99.2	22.1 97.4	85 97.2	96.5 97.4
FaceOcc1	67.2	79.4	80.3	27.2	56.4	100	98.8	100	96.2	100	100	100	90.6	100	100	94.2	100	100	100	100	100
FaceOcc2	99.4	99.8 100	99.5	100	78.9 62	100	97.8	62.4	93.5	99.6	100	98.6	1.11 5.67	91.9	99.8	100	99.6	93.6	90.4	61.7	95.3
FleetFace	54.7	65.5	55.6	64.5	44.1	78.1	57.3	58.7	64.2	66.9	66.5	70.3	5.23	77.8	94.3	61.8	71	66.3	67.8	76	74.5
Football	97.5 100	77.3 91.9	84.3	77.1 43.2	74.9 36.5	89.8 32.4	68 32.4	63.8 40.5	98.3 68.9	70.2 94.6	79 39.2	78.5 35.1	0.276 79.7	95.6 90.5	100	98.3	78.7	87.8 39.2	76.5 39.2	79 39.2	79 37.8
Football1 Freeman1	12.6	18.4	17.8	32.8	23.3	20.2	14.7	13.8	22.7	16.3	35.3	28.2	19	22.1	65.3	29.8	95.9 <b>86.5</b>	62.6	53.1	54.3	43.6
Freeman3 Freeman4	28.9 17	15.7 20.1	33 18	91.7 17	64.6 21.6	17.6 18.7	31.3 15.9	33 17.3	1.09	27.8 18.4	31.3	26.1 16.6	30.7	33 28.3	31.1 41.3	29.6 45.9	31.3 45.2	55.9	70.4 90.5	100 79.5	100 74.6
Girl	48.6	14.4	25.2	86.8	72.6	97	29	49.8	17.4	74.2	30.6	100	46.2	90.4	97.6	97.4	46.6	77.6	79.8	100	99.6
Girl2 Gym	7.13	8.13	7 6.91	15.5 4.95	27.6 35.6	35.9 11.1	7.27	7 26.9	7.27	7 34.3	7.27	77.5 35.1	55.4 29.3	78.6 37.9	7.47 2.35	7.47	7.43	7.4	87.8 41.3	71.5 35.5	97.5 6.13
Human2	9.31	16.8	9.13	93.2	48.8	71.5	54.4	17.6	19.5	18.3	55.8	56.9	29	83.4	94.5	80.4	95.4	53.5 97.8	99.7	94.9	94.2
Human3 Human4	0.53	1.24	0.53	9.15	0.53	1.06	0.53	2.53 19.2	0.471 59.4	0.471 51.3	2.77	93.6	6.77	65.8 49.5	79.3	3.24 60.9	3 91.8	3.18 100	77.8 91	39 60.3	87.8 75.3
Human5	34.2	5.05	7.57	98.9	60	33.9	34.2	24	28.5	23.6	24.3	24	1.4	34.2	8.27	24	34.4	96.5	99.9	99.2	99.6
Human6 Human7	22.5	20.1	21.2	43.9 29.2	30.4	22.3	22.5 41.2	22.6	21.6 50.4	22.5 40.8	45.6 42.4	25 44.8	22.5 15.6	22.3 41.2	26.9 28.4	22.5	98.1 100	92.2 100	47.1 100	89.5 100	96.2 100
Human8	13.3	7.81	13.3	8.59	9.38	13.3	4.69	25.8	11.7	30.5	100	67.2	29.7	30.5	99.2	30.5	100	100	100	100	100
Human9 Ironman	14.8	23	13.4 3.61	18.7	20.3 8.43	4.92	22.6 7.23	19.7	19 8.43	23.9	23.9	19	16.7	19.7 51.8	47.2 9.64	23.9	9.64	46.2 3.01	46.6 4.22	12.1 25.9	100 88
Jogging	22.1	91.2	21.5	22.8	96.4	95.8	17.3	22.5	22.5	22.5	22.5	96.7	22.5	91.5	96.7	96.4	22.5	97.1	97.1	25.9 97.1	97.4
Jogging Jump	15 5.74	15.6 4.92	15.6 5.74	18.2 7.38	95.4 4.1	16.3	97.7 8.2	18.2	99.3 8.2	16 7.38	18.2 8.2	99.7 8.2	19.5	86 8.2	97.1 6.56	100 9.84	18.6 7.38	99.3 2.46	98.7 2.46	94.1 4.92	100 9.84
Jumping	91.7	7.67	11.8	5.75	92.3	88.5	4.79	4.79	10.2	28.1	6.07	24.6	5.43	99	92.7	99.4	21.4	95.8	95.5	99.7	99
KiteSurf Lemming	98.8 44.8	41.7	83.3 47.4	31 16.7	38.1 63.4	53.6 63.8	95.2 79.3	100 29	90.5 29.5	32.1 44.2	39.3	90	89.3 74.4	98.8 88	45.2 89.1	45.2 26.7	90.5 26.8	64.3 26.3	39.3 96.4	100 90.5	100 95.8
Lionor	23.3	60.1	22.9	68.8	75.5	40.5	40	28	37.7	98.1	40.9	81.2	42.7	98.3	49.9	81.2	62	98.6	98.4	97.9	96
Man Matrix	22.4 9	100 2	22.4	100 7	28.4	100 11	100 13	100	24.6	100 13	100 18	100 32	47 8	100 36	100 31	39	100 33	100 37	100 29	100 35	100 62
Mhyang	91.2	97.1	77.5	100	90.3	100	90.3	91.7	93.7	100	99	100	76.4	96.9	99.1	100	98.5	99.7	99.9	100	100
MotorRolling MountainBike	6.1 100	9.15	6.1 35.1	9.76	17.7 25	15.2 94.7	7.32	15.9 100	11.6 100	7.93 98.7	6.71 100	7.93 93	8.54 12.3	9.76 81.1	6.1 99.1	59.8 100	6.71 100	7.32	7.32 100	7.32 99.6	7.32 97.8
Panda	0.415	0.415	0.415	0.415	0.415	0.415		0.415	68.7	14.6	13.4	23.6	65	39.2	26.7	20.4	27.9	13.6	12.5	11.9	31.4
RedTeam Rubik	34.9 76.8	28.5 43.9	35.5	77.2 91	35.3 47.4	39.8 31.9	39.1 14.6	40.5 81.8	40.7	37.6 81.4	70 77.2	56.9 50.9	30.3	39.2 64.5	69.8 98.5	29.6 72.9	69.1 75.3	97.5 16.5	94.7 55.5	93.7 96.4	93.1 99.4
Shaking	17.5	69.9	82.5	23.3	3.29	52.9	0.822	67.9	53.2	1.37	100	1.37	3.01	93.2	99.2	85.5	1.64	1.1	94.2	98.1	4.93
Singer1 Singer2	27.6 79	27.6 100	27.6 69.7	76.2	98.6 11.2	29.9 3.83	29.9 55.5	27.6 3.55	21.9 97.5	27.6 96.7	100	3.55	28.5	27.4 3.83	72.6 100	27.6	100	98.6	98.9	3.55	3.55
Skater	40.6	83.8 2.76	42.5	41.3	50 35.2	73.8	78.8 11.7	51.9 73.6	81.9 57.2	81.3	30	71.9 61.6	69.4 78.4	65	42.5 72.2	88.8	76.9 35.2	68.8	61.3	79.4 52.4	75 76.8
Skater2 Skating1	4.83 15.5	18.3	16.3	32.9 73.3	35.2 9	48.7 31.3	34	73.6 35.5	57.2 52.8	36.3	29.2 52.3	52.5	78.4	38.3	72.2 82	37.5	35.2 50.7	53.8	61.1 47	52.4 43.8	76.8 38.5
Skating2	2.96 12.9	22 14.2	12.3	37.2 15.2	5.92	17.8 19.5	3.17	17.3 15	32.1 16.5	27.9 27.9	38.1 10.4	48.2	34.5	13.1	8.25	46.9	53.5 12.1	53.5	56.9 22.4	60 27.7	59.4 29.8
Skating2 Skiing	9.88	3.7	6.17	15.2	7.41	19.5	6.17	9.88	9.88	7.41	4.94	34.7 4.94	2.96 51.9	32.1	9.88	25.2 42	12.1	4.94	4.94	27.7 11.1	30.9
Soccer	17.6	9.18	21.9	10.5	11.2	18.1	16.8	32.9	13.8	39.3	38.8	33.9	13.5	21.4	15.3	46.7	24.5	57.9	84.7	84.4	77.3
Subway Surfer	100 86.2	82.3 40.4	1.86	97.1 2.13	57.7 82.7	97.7 81.4	22.3	94.7	98.9 96	39.9	22.3 29	85.9	90.9 22.3	97.7 38.3	93.9	43.6	26.3	99.4 95.7	99.4 93.9	98.9 96.8	100 96
Suv	5.19	52.8	5.19	79.2	95.8	47.3	56.3	53.4	53.7	98.4	98.4	98.4	12	79	98.4	98.3	98.4	98.4	98.2	83.3	97
Sylvester Tiger1	55 33.2	92.9 7.74		44.9 15.8	84.8 23.2	96.3 83.7	98.9 25.8	74.2 87.1	94.5	82.1 85.7	69.4 59.3	78.4 83.1	29.4	92.1 91.7	92.9 90.5	84.7	65.8 98	83.3 99.1	85.8 96.6	90 99.7	95 99.7
Tiger2	26.3	11.2	80.5	12.6	20.3	69.3	25.5	66	76.2	36.4	29.6	49.3	44.7	49.3	72.3	55.6	87.4	95.3	94.5	64.4	89.3
Toy Trans	38.7 41.9	28 40.3	40.6 35.5	50.9 40.3	77.9 39.5	35.8 41.1	32.8 38.7	39.5 <b>54.8</b>	30.3	43.2 47.6	90 32.3	68.3 50.8	1.11 38.7	38.7 44.4	79 35.5	43.5	90 51.6	79.7 40.3	58.3 36.3	70.8 41.1	84.1 48.4
Trellis	47.6	44.3	51.8	85.8	40.6	54	1.23	66.3	86.8	84	97.7	100	71	81.2	92.3	83.5	99.3	96.5	95.3	96.3	99.1
Twinnings Vase	34 16.2	26.3 15.9	32.7 15.9	47.8 17.7	54.8 34.3	54.1 15.5	24.2 15.1	57.3 16.2	59.9 15.9	54.4 16.2	100 43.9	96.6 21	53.7 15.5	57.7 16.2	74.3 20.7	62.6 16.2	97.7 <b>66.4</b>	43.5 52.8	99.4 57.6	71.3 49.8	99.6 42.1
Walking	55.1	54.4	55.1	99.8	35.2	52.4	54.9	49	81.8	51.5	99.8	99.8	53.6	53.6	98.3	53.2	99.8	99.8	99.8	99.8	95.4
Walking2 Woman	38.2 93.3	38.4 83.9	38.2 93.5	39.8 88.6	20.8 32.8	43 93.5	43.2 90.3	38.4 92.8	93.6	38 93.6	100 93.3	51 92	35.6 16.6	37.8 93	40.6 93.1		93.1	92.3	100 93.3	43.4 99.2	100 98
Average	41.4		35.9		46.5		44.9	49.6	54	54.9	60.6	64.7	36.4	63.4		65.5		72.9	76.7	77.3	82.4

**Table 2.** A per-video comparison on the Temple-Color dataset [17] with 128 videos. The results are shown in terms of overlap precision (OP) (in percent), which corresponds to the PASCAL criterion. The best and second best results for each video are shown in red and blue font respectively. Our approach achieves a significant gain of 4.6% in mean OP, compared to the second best tracker (SRDCFdecon).

Video	EDFT [8]			ASLA [14]	TLD [15]	Struck [11]	CFLB [9]	ACT [7]	TGPR [10	KCF [13]	DSST [2]			MEEM [26]	LCT [19]	HCF [18]		SRDCF [4]	SRDCFdecon [5]	DeepSRDCF [3	С-СОТ
Airport Baby Badminton	38.5 29.7 17.8	28.4 13.2 91.9	40.5 29.7 17.6	90.9 92.7	43.9 61.5 72.9	41.9 27.4 58	1.35 29.7 7.25	40.5 29.7 54.7	42.6 32.1 96.5	42.6 27.4 96.4	47.3 97 72.2	43.2 91.2 85.1	42.6 29.7 83.9	41.2 27 90.8	42.6 29.1 95.3	29.1 89.8	95.3 88.8	90.9 77.4	45.3 83.4 78.9	44.6 95.9 86.4	44.6 99 89.3
adminton all	17.8 7.09 2.3 6.04	91.9 0.142 1.28 0.864	17.6 4.26 2.3 13.1	92.7 29.6 2.56 20.2 59	72.9 3.55 1.28 10.4	58 64 6.91 0.345 58	7.25 59.4 2.56 0.173	54.7 49.6 1.53 42 63.2	96.5 85.7 2.3 40.4	96.4 9.93 1.53 36.1 56.1	72.2 41.8 1.28 6.04	85.1 86 1.79 44.2	83.9 86.4 11.8 67.2	90.8 68.5 25.1 53	95.3 80.6 1.28 54.1	89.8 82.7 28.6 87 67.9	88.8 88.9 2.3 63.4	77.4 65.2 1.28 57.5	78.9 78.3 5.12 91.5	86.4 54.9 11.3 83.1	89.2 2.05
dl dl	6.04			20.2 59		0.345 58		42 63.2		36.1 56.1				69.3	68.4	87 67.9		57.5 69.3	91.5 69.3	83.1 69.3	90.8
ill isketball	69.3 5.02 31 11.7 6.59	1.49 87.9 10.5 12.3	4.83 71.6	0.372 16.7 11.5 15.2	0.372 33.8 7.46 6.81	2.97 49 11.9 16.5	2.42 8.97 11.1 9.23 59.6	0.372 48.7 14.5 10.8	4.65 88.7 9.68 10.8	1.3 89.8 19 22.9	2.23 12.1 16.7 16.5	1.3 96.7 34.7	4.65 89.5 11.1 46.2 72.3	4.65 83 13.5 5.27 94.1	3.35 99	5.39 99.9 19.4 33.2 76.4	4.09 87 33.3 39.3 91.4	5.02 41.4	5.02 96.1	5.02 28.3	4.09 98.9
sketball sketball	11.7 6.59	10.5 12.3	12.1 9.01 9.3	11.5 15.2	7.46 6.81	11.9 16.5	11.1 9.23	14.5 10.8	9.68 10.8	19 22.9	16.7 16.5		11.1 46.2	13.5 5.27	19.4 51	19.4 33.2	33.3 39.3	41.4 56.9 35.4	67.5 47.7	28.3 48.8 43.1	73.: 45.1
asketball se	49.4 57.8	57.1 78.9 55.4	9.3 14.4	22 38.9			59.6 37.8	67.6 43.3 20.3		69.8	34.7 26.7 60.9	76.6 22.2 78.6	72.3 95.6 47.2	94.1 54.4	59 28.9	76.4 28.9	91.4 85.6 86	82.8 43.3 96.7	87.5 57.8	64.6 41.1 75.6	92.1 47.8
ke ke	57.8 25.5 71.4 2.34 19	55.4 4.12	3.5 14.4 21 39.5 2.34 19	95.2 97.1	98.9 24.7 12.9 15.8	83.3 30.6 75.9 2.34 21.8	37.8 19.9 11.5 2.34 19	20.3 74.7 2.34	91.1 35.4 91 2.46 63.1	20 19.6 76.7 2.34 19	60.9 99.6	78.6 100	47.2 74.2	54.4 44.6 75.7 2.34	28.9 19.2 76.7 2.34	28.9 33.6 76.7 9.98 47.5	86 100	96.7 100	94.8 100	75.6 98.9	72 100
ke	19	4.12 2.34 19	19	97.1 13.4 52		21.8	2.34 19	43	2.46 63.1	19	99.6 13.5 93.9	10.1	74.2 2.34 19	41.3	19	9.98 47.5	13.8	53.8 96.6	90.3 97.2	90.4 91.6	85.5 52.0
ird	2.77 94.9 19.2 5.04	2.22 16.2	21.9 94.9	3.05 9.09 13.7	1.39	2.77 49.5	12.7 47.5	18.3 99	46.5 57.6	21.6 54.5	7.48 52.5	35.7 55.6	76.7 99	46 98	2.22 76.8	56.2 98	2.77 88.9	15 57.6	22.4 65.7	19.4 96	100
oard oat oat	5.04 44.4	83.1 5.04 39.8	20.1 5.04 44.9	6.1	5.35 16.2	81.9 5.04 52.9	5.04 51.2	99 83.9 5.04 53.6	10.9 5.04 45.4	92 5.04 44.9	81.6 5.57	82.4 39.3	79.9 4.51 27.2	89.3 5.04 51.2	92.3 5.04 44.4	92.8 5.04 52.4	92.8 4.77 61.7	92.1 50.7 58.3	50.4 59.5	90.1 57.3 60.9	83.4 55.4 60.5
alt w	1.71 98 10.5 24.6	1.14 42.5 9.37 34.7	4 48.3	1.43 43.9 10.2 24.1	42.5 17.7 96.5 10.5 33.9	1.43 97.5 56.2 29.1	2.29 98.5 10.5 91.9	100 95	2.29 95.5 10.5 90.1	94.3 99.2 10.5 87.8	100	99.7	96 96.3 9.92 93.9	88 99.2 11.3	98.6 99 10.5	98 99 10.2 90.4	100 100 10.2 88.1	1.43 100	1.43	74.6	90.6
sstation	10.5	9.37	4 48.3 10.5 24.8	10.2	10.5	56.2 29.1	10.5	95 11 26.3	10.5	10.5 87.8	100 100 10.2 92.4	10.2 23.8	9.92	11.3	10.5 88.1	10.2	10.2 88.1	90.4 97.5	10.2 96.7	82.4 99.2	9.95 95.4
arDark arScale				71.8 28.3	27.5 75.4	100 43.3 27.7 98.8 6.33	98.7 44.8	100	100 47.6 28.1 97.7 6.33			99.7 100 10.2 23.8 58.3 59.9 28.3 96.5 7.69		100 44.8	97.7 44.8		99.6		100 85.7	100 81	
archasing archasing	98.4 44.8 28.1 99.5 6.33 17.1	44.8 28.1 96 6.33	44.8 28.1 100	28.3 100	32.1 72 81.7	27.7 98.8	28.1 100	28.7 97.4 6.33	28.1 97.7	44.4 28.3 91.6 6.33	84.5 28.3 99.5	28.3 96.5	2.04 44.4 25 84.8 6.33	44.8 28.1 98.3 6.33	44.8 28.7 98.6 6.33	44.4 28.7 96 6.33	28.3 99.8	80.6 28.3 99.1	93.2 99.1	81 28.1 99.1	80.3 28.3 99.3
archasing harger	6.33 17.1	6.33 28.9	6.33 18.1	6.79 22.1		6.33 19.1	6.33 13.1	36.6		19.5	79.5	56.4		6.33 22.1	29.5		99.8 100 80.2	83.2	100 71.8	100	78.3
oke ouple	14.4 21.4 75	28.9 4.12 10.7 11.7	18.1 8.59 8.57 64.2	22.1 14.4 10.7	47.1	19.1 94.5 60.7 95.8	63.2 63.6	64.3 10.7	91.8 10.7	72.2 24.3 95	83.8 10.7	79.7 45.7	47.8 63.6 97.5	22.1 95.5 75.7	91.4 50	91.4 74.3 95	78 67.9	61.5 92.9	56.4 94.3	18.8 50.5 77.9	54 72.1
rossing ap		11.7 100 1.18	100 1100	100 100 1.18	45.8 100	95.8 100 1.18	46.2	88.3 100 1.18	98.3 100 1.18	95 100 6.21	100 100 1.18	100 100 1.18	97.5 100 1.18	98.3 100 1.18	96.7 100 1.48	95 100 1.18	100 100 1.48	100 100 1.48	100 100 1.48	100 100 1.18	100
avid avid3	1.48 55.4 87.3	43.7 35.3 4.23	23.4	95.3 52.4 4.23	91.1	24 33.7	23.8 64.7	62.6 87.7	62.6 99.6	62.2 99.2	1.18 100 53.6	95.8 100	39.1 100	62.6 94	62.6 96.4	60.1 100	96.2 100	98.7 100	98.9	100	100
er ving	63.4		1.18 23.4 74.2 31 21.2		91.1 32.1 78.9 16.5	21.2		20.8	100	81.7	84.5 28.1	88.7 17.7	9.86		81.7 30.3	100	100 100 18.6	100 22.1	100 22.1	100 100 24.7	100
oll igle	49.3 20.5	46.7 11.6 1.47	35 33 59.5	98.7 38.4	69 36.6	52.7 28.6 97.1	29 72.5 33 97.1	49.6 35.7 97.8	51.3 45.5	55.2 2.68 97.1	99.6 2.68	67 2.68	18.3 18.8	18.2 72.9 85.7 96.7	72.9 2.68 96.8	72.9 74.1	99.7 32.1 99.9	99.6 29.5 99.5	99.5 16.1	90.1 25 97.3	99. 5.3i
ectricalbike sceOcc1	49.3 20.5 97.8 67.2 3.71	1.47 100	59.5 80.3 3.71	98.7 38.4 100 29 4.35	69 36.6 93.4 51.1	97.1 100	97.1 98.8	97.8 100	51.3 45.5 99.6 98 3.71	97.1 100		100	18.3 18.8 1.83 90.6 3.23	96.7 100	96.8 100	28.6 72.9 74.1 94.5 94.2 3.71 79.1 61.1 15.4		99.5 100	100 100	97.3 100	100
ice	3.71 20.3	3.55 22.3	3.71 28.4	4.35 8.78		3.06 25	98.8 3.06 39.2 2.74	3.87 8.78	3.71 8.78	4.35 10.1	100 4.35 52.7	4.35	3.23 10.1	3.55 73.6 58.9 57.4	3.71 8.78	3.71 79.1	4.35 85.1 65.6	100 4.52 89.9	80 84.5	79.8	78.5 83.1
sh sh	20.3 4.99 15.2	22.3 5.49 15.2 85.1 57	28.4 5.24 34.2	8.78 5.24 15 47.3 29.4	8.78 6.73 19.4 35.1 80.2	25 29.7 14.1 32.4 96.8	2.74 14.8 32.4 36.4	8.78 6.98 15.2 40.5	8.78 65.1 14 94.6 83.6	10.1 4.24 14.8 94.6	52.7 4.99 15 39.2 23.8	89.9 32.7 15.4 35.1	10.1 65.6 72.3 79.7	58.9 57.4	8.78 5.99 14.5	61.1 15.4	14.5	89.9 17.7 14.1 39.2 17.4	84.5 11.5 55	93.2 20.4 14.8 39.2	83. 43. 32. 37.
otball1	100 48.6	85.1 57	25.2	47.3 29.4 41.2	35.1 80.2	32.4 96.8 17.3	36.4	49.8 5.93	94.6 83.6		23.8		46.2	90.5	95.4	97.4	64.4	39.2 17.4	52.7 81.8 7.27	39.2 100	99.0 77.0
rimov sitar	95.9	28.9 88.1 98.1	5.67 91.4	90.3	97	97.4 68.1 38.3	96.6	97.8	97.8	98.5	6.93 97.4 54.6 78.2	45.2 97.4 98.1	83.7 17.2 80.5	94.4	7.4 97.8 90.4 83.7	96.3	92.2 97.1 87.1	7.4 98.9	97.4 65.2	99.3 95.5	- 00
/m and	6.2 95.9 94.9 11 69.3	5.48 59	17.9 60.2 93.3 34.3 26.3 39.5	90.3 51.4 43.9 16.4 2.24 47.4 11.3 48	21.1 97 17.3 42.8 12.3 8.73 52.6 14.3 2.63	38.3	7.2 96.6 79.9 17.6 14.3	19.2 16.8	6.33 97.8 63.9 80.7 32.4 97	7.4 98.5 91.1 77.4 13.1	78.2 16.8	98.1 85.4 16.8 97	59	94.4 96.5 77.8 16.8		97.4 7.4 96.3 92.3 87.9 15.6	87.1 16.8	98.9 64.9 44.9 16.8	69.6 18.9	21.9 14.8	95.1 57.2 82
and and	86.3 92 75.7 56.6 14.2	30.7 0.398	93.3	2.24	8.73 52.6	26.6 4.74 39.4 53.7 0.658	1.25 41.4	2.24 53 88.3	97 92	92.8 61.8	16.8 13.5 61.4	97 83.3	99.3 87.6	98 95.6 86.3	97.8 92 69 90.1 76.4	94.3 84.5 89.3	16.8 97.5 75.7 66 94.7	99.8 67.3	99.5 87.6	99.5	100 94
ırdle ırdle	75.7 56.6	15.5	26.3 39.5	11.3 48	14.3 2.63	53.7 0.658	3.67 54.6	88.5	84.5	90.7 94.7	61.4 63.3 67.8	83.3 87.7 97	95.3 64.5 72.2	98.4	69 90.1	98.4	66 94.7	83 98.4	90.8	79.7 94.1	94 90.2 96.3
skater onman	14.2 4.22	12 3.61		71.4	49.2		43.8	52.2 24.7	67			82.6 11.4 96.7	72.2 4.82	69.6 51.8	76.4 9.64	82.8 60.8		41.6 56	55.2 9.64	52.8 25.9 97.1	85 88
gging1 gging2	4.22 22.1 15 48 8.06	3.61 35.2 13.4 45.8 2.07	3.61 21.5 15.6 47.8	12.7 22.1 15.6	8.43 96.1 87	6.02 22.1 16.3 48 1.24	16 97.7	24.7 22.5 18.2 48	22.5 99	15.1 22.5 16 48	14.5 22.5 18.2	96.7 99.7	4.82 22.5 19.5 45.8	91.5 86	9.64 96.7 97.1 48 34.3	96.4 100	9.64 22.5 18.6	56 97.1 97.7 100 33.9	97.1 100	97.1 94.1	97.
ice te	8.06	2.07		14.7	11.2	1.24	22.9		91.3		100	30.2		47.8 96.7	48 34.3	48 43.6	44.9	33.9	33.1	12.8	92
ite	78.1 57.6 18.9 44.8 23.3	54.4 97.3 14.4 58.7 0.517	28.1 38.3 16.2 47.4 22.9	14.7 54.4 77.5 13.9 16.8 58.6	82.1 100 6.19 63.8	16.3 98.7 5.33 64.3	7.23 16 97.7 51 22.9 84.5 98.9 16 79.3	89.4 57.6 17.9 29 28	7.23 22.5 99 100 91.3 95.6 88.8 20.6 26.9 42.2	55.2 97.7 14.9 44.2	97.7 16.3 27.2	98.9 96.4 17.7 90.7	86.8 96.2 26.3 74.4	51.8 91.5 86 47.8 96.7 88.1 98.3 15.8	91.3 100 15.8 78.3	87.4 99.8 17 26.7	90.3 99.6 11 26.8 84.5	98 99.1 16.7	98.1	93.8 99.8	97.
mming	44.8	58.7 0.517	47.4	16.8 58.6	63.8	64.3 40.6	79.3 40	29	26.9 42.2	44.2 98.1		90.7		98.3		26.7 81.2	26.8 84.5	98.8	91.3 91.9	99.8 22.7 90.5 97.9	95. 96
ogo atrix	12.8 9 41.2	12.8 1 30.9 36.9 15.7		19.8 11 20.6 89.1 18.1	74.6	13.6 11	12.0		11.8 9	12.8 13	53.4 17 25.4 14.2	35.7	10.7 8 40.4 52.9 87.7	12.6 36 54	12.5 31 47.1 64.4 100	11	84.4	84.4 30 53.3	82.3 25	84.4	81 62
essi ichaeljackson	41.2 36.4 93.1	30.9 36.9	6 47.4 36.1 62.7	20.6 89.1	21 49.1 61.8 9.71 12.8	13.6 11 27.9 50.6 100	2 20.2 62.3 19.6	1 4.78 53.9 100	9 62.1 94.1 95.1 15.5 15.9	13 19.9 100	25.4 14.2	22.4 90.1 98.5 10.7 7.93	40.4 52.9		47.1 64.4	44.1 87.3 99	51.1 92.1 55.4 43.7 6.71	53.3 86.3	68.4 54.5 57.8	65.4 54.2 85.8	69.1 53.1
icrophone icrophone	99	15.7 4.85 6.1	62.7 28.2 6.1	18.1 24.3 8.54	61.8 9.71	0.971 16.5	19.6 4.85 7.32	12.6 15.9	95.1 15.5	99.5 17.5 7.93	69.6 41.7 6.71	98.5 10.7	87.7 100 8.54	99 74.8 9.76	100 13.6 6.1	99 11.7	55.4 43.7	86.3 90.7 65 7.32	4.85	85.8 35.9 7.32	18. 7.3
otorRolling otorbike	6.1 23.8	6.1 2.84 97.4	6.1 23.8 35.1	8.54 99.8 63.6	9.59	23.6 97.4	23.8	15.9 23.8	15.9 24	23.8	6.71 23.8	23.8	8.54 23.1 12.3	30	6.1 23.8 96.5	64.7	6.71 23.8	23.8	6.71 67.5	7.32 23.6	7.32 23.2 97.2
ountainBike anda	100 61	2.49	35.1	63.6 44.4	20.2 78.8 21.6 100 74.6 5.42	97.4 61	97.4 51.9 27.4 59.9	52.3 22.5 73.9	3.73 32.2 67.6	98.7 2.49	2.49	93 2.9	12.3 51.9	81.1 94.2	96.5 36.5	100 53.1 33.4 66.2	92.5	98.2 97.1	98.7 94.6 54.7	99.6	97.2 99.1 50.2
ane ate ate	61 27.1 68.3 98.9	2.49 12.7 52.1 43.6 4.22	22 12.1 71.8 95	9.95 92.3 85.1 97	100 74.6	61 18.7 2.11 0.552 97	59.9 100	73.9	67.6	2.49 29.6 72.5	2.49 33.1 68.3	68.3 95 4.22	51.9 14.1 73.9 74.6	74.6	36.5 30.6 70.4	66.2	70 72.5	22.2 100 36.5 48.8	99.3	38.6 99.3	100
iol iol			98.2 25.6		5.42	97	99.4	4.22 0.752	4.22	3.61 0.752	99.4 4.22 0.752	4.22		94.2 14.1 74.6 97.8 96.4 98.5 71	3.61 0.752	99.4 4.22 0.752	4.22 0.752	48.8	38.1 91.6 4.51	44.2 97 72.9	100 41. 95.2 75.5 40.
iol ilwaystation	5.65 2.91	0.806	1.61 2.91	0.806 2.91	1.61	8.27 0.806 7.26	0.806	0.752 1.61 3.39	0.806	0.752 1.61 3.39	0.806 3.15	0.752 1.61 3.15	1.61	71 8.23	1.61	1.61 75.8	2.42 7.99	2.26 0.806 12.6	8.06 13.1	72.9 12.9 11.1	12.
ng ilor	99.2 5.65 2.91 100 71.1	0.806 3.15 5.97 9.95	25.6 1.61 2.91 75.6 12.4	99.5	91.7 1.61 22.3 100 11.9	46.5	96.3	98	100 4.22 0.752 0.806 3.15 28.4 10.2	39.6	100 41	98.3	15.8 1.61 94.4 4.98 99.3	99.8	1.61 3.39 100 41	1.61 75.8 100 97.5	100	99.8	100 100	100 98.5	98.
aking nger1		48.5 27.6	82.5 27.6 69.7	36.7 100 100	3.29 97.2		0.822 29.9 55.5	67.9 27.6 3.55	64.1 22.8 99.5	1.37	100 100 100	1.37 57.8 3.55	3.01 28.5	93.2 27.4	94.2 27.6 100	85.5 27.6	1.64 100 100	95.6 100	96.2 100	98.1 100	4.9
nger2 nger	27.6 79 98.1 27.7	48.5 27.6 65.3 93 27.6	31.8	21 18.6	3.29 97.2 9.56 9.35 59.5	29.9 3.83 70.6 13.8	55.5 15.4 7.81	3.55 17.3 8.31	99.5 98.6	27.6 96.7 86.9	100 14 7.81	3.55 100	3.01 28.5 1.37 96.3 5.51	27.4 3.83 98.6 27.1	99.5 24.9	85.5 27.6 4.1 90.2 7.71	90.2	3.55 93.9 12.8	3.55 94.4	3.55 93	3.50 95.2
ating1	27.7 15.5 17.4 50.6	16.3	8.51 16.3 16.1	18.6 74 15	59.5 44.5 21.5 14.7	13.8 31.3 33.4 31.5	34	8.31 35.5 18.2 9.05	98.6 9.81 50 68.2 57.7	8.91 36.3 65.5 28.6	7.81 52.3 4.81 7.82	100 23.2 52.5 70 9.05		27.1 38.3 75.7 74.8	35 78.9	7.71 37.5 78.6 33.7	91.1 83 67.8	12.8 21.5 44.3 84.1	66.9 44.8 11	57 43.8 10.6	38.1 87.1
ating2 ating ating	50.6 27	41.1 25.2	11.5 5.63	6.85 7.65	21.5 14.7 4.83	31.5 6.24	2.26 5.13 5.43	9.05 5.43	57.7 28.6	28.6 8.65	7.82 5.63	9.05 41.9	32.2 67.7 32.4	74.8 37.8	45 12.9	33.7 39.6	84.6	84.1 37.4	86.3 34.8	10.6 62.1 5.43	79. 22.
ating iing iing	0.66	3.7	6.17		7.41	4.94				7.41	4.94	4.94	51.0		11.1	42	12.3 100	6.17	8.64	11.1	
iing yjumping ccer	77.9 13.3 17.6	47.9 3.41 15.3 12 97.1 75 10.5 33.1 9.9 11.5	13.3 14.9 21.9 11.1	90.2 5.76 13.8 12 21.7	83.2 41.2 8.93 8.55 97.7	75.5 18.7 14 10.8 97.1	37.6 21.5 13.5 6.27	58.9 3.94 32.9 11.7	74.4 36.6 13.5 11.7 97.7	73.4 6.4 39.3 9.12	99.6 14.9 15.3 33.3	36.1 33.9 45	80.4 46.4 13.5 3.7	73.4 31.4 21.4 12 97.7	78.9 3.09 15.3	65.2 32.7 46.7 12 100	37.7 24 42.7	100 6.5 82.1	38.1 22.2	26.9 84.4	99. 34. 77. 68.
óderman bway		12 97.1		12 21.7	8.55 97.7	10.8 97.1		11.7 22.3	11.7 97.7					12 97.7		12 100		52.1 22.3 77.7 97.7 85.7 43.6 8.18	98.3	55 98.9	
itcase nshade	39.1 37.8 18.8 8.17	75 10.5	41.8 47.1 18.8 8.42 6.91	39.7 55.2 35.3 19.3	91.3 69.2 39.1 7.92 2.56	38.6 98.8	39.1 100 73.7	22.3 80.4 100 17.3 7.92	39.1 97.7 3.01 31.4	98.3 14.3 4.21 10.2	69 98.3 18.8 6.93 30.7	78.3 97.1 14.3	39.1 91.3 12.8 67.8	78.8 100	78.3 96.5 16.5 51.7	79.3 98.3 63.2 59.4 9.97	78.3 98.3 85 52.7	77.7 97.7	78.8 98.3	78.8 97.7	75. 97.
perMario rf	18.8 8.17 9.46	33.1 9.9	18.8 8.42	35.3 19.3 10.5	39.1 7.92	10.9	73.7 16.6 11.5	17.3 7.92	3.01 31.4 32.2	14.3 4.21	18.8 6.93	14.3 83.9 8.44	12.8 67.8	69.6	16.5 51.7 13.6	63.2 59.4		85.7 43.6	67.8	100 37.9 15.1	75 30.
rf vf		21.9	6.91 12.2		2.56 21.9 9.63 7.58	26.1 25.8	11.5 55.2 7.41	60.9	32.2 64.9	10.2	30.7 15.4 20.7 1.01	8.44 14.3	49.9 57	39.9 42.3		9.97 54.5 12.6 1.52		8.18 48.7	6.14 20.4 6.67	15.1 12.9 13.3 2.02	45
bleTennis nnisBall	18.3 11.9 3.54 4.17 17	21.9 31.1 0.505 1.04 73.1	12.2 7.41 1.52 3.13	32.6 12.6 3.03 2.43 95.6	7.58 2.78	25.8 8.89 3.54 0.347 67.6	5.05 2.43	8.89 1.52 1.74	0.505	10.4 23.7 2.02 0.347		14.3 7.41 2.02 0.347 91.6	3.03 2.78	42.3 20 1.52 1.74 94.5 100 81.4	14.4 14.8 2.02 1.04	12.6 1.52 0.347	40.9 31.1 1.52 1.04	48.7 8.89 1.52 1.74	0.67 1.52 2.08	13.3 2.02 3.13	12: 1.5 3.1
nnis nnis	17 91.8			95.6 89.8	2.78 79.7 38.7 16.2 1.33 15.3	67.6 98.4	2.43 59 70.5	87.2 41	98.2		61.5 100	91.6		94.5	96	94.1 99.7	100	92.1	2.08 89.9 98.4	69.2	79.
nnis nunder	91.8 85.3 85.6 37	5.88 53.3	96.4 10.3 50.7 96.3	96.6 8.27 17.5	16.2 1.33	98.4 86.3 0.533	70.5 96.1 22.1 35	62.7 99.5	98.2 99.7 9.8 98.9	100 8.82 95.5	67.2 70.1	100 69.6 100	99.3 97.5 96.3		8.82 69.3	8.82 100	54.9 99.5	98.7 86.8 100	98.4 89.7 100	95.4 88.7 100	88.
ger1 ger2		14.1			29	84.2		36.2 66	96.6 87.1	98		58.8 49.3	29.1	82.5 49.3	92.9	87.3 55.6	97.7 86.8	98.3 92.3	98.6 93.4	98.9 64.4	84.
rus yplane	96.2 8.89 47.6 55.1	92 0.247	57.2 6.17 51.8 55.1	23.1 8.4 66.6	6.06	9.09 8.89 31.8 52.4	17.8 9.88 1.23 54.9	95.8 9.63	96.2	96.2 9.63 84 51.5	29.6 94.7 9.63 97.7 99.8	95.8 9.63	87.5 8.64 71 53.6	49.3 96.2 8.89 81.2 53.6	89.8 9.88 81.4 53.9	96.6 24.2 83.5 53.2	97.7 8.89 98.9 99	95.1 8.89	98.5 19.8 97.2	96.6 9.38 96.3	97. 9.6
ellis alking	47.6 55.1	48.3	51.8 55.1	66.6 99.8 41.4	27.7 59.8 30.1	31.8 52.4	1.23 54.9	49	46.9 83 65.5	84 51.5	97.7 99.8	100 99.8 51	71 53.6	81.2 53.6	81.4 53.9	83.5 53.2	98.9 99	96.7 99.3	97.2 99.8		95.
alking2 oman	38.2 93.3 10.2 20 7.96	37.4 35 5.53 19.8 1.49	38.2 93.5 5.11 19.8 4.48	41.4 63.7	25.8 28.8 21.7 52				93.5 4.68 0.441			51 92		37.8 93 17.4 34.1 5.47		41.4 93.5 8.09 18.7 2.99		95.1 8.89 96.7 99.3 100 92.6 9.36 29.1 5.47	93.6 35.3	43.4 99.2 10.2	98 10.
)	20	5.53 19.8	5.11 19.8	63.7 4.26 29.5 2.49	21.7 52	93.5 10.6 44.7 50.2	93.5 9.36 20 1.99	92.8 4.26 20 2.49	0.441	93.6 5.11 20.9 2.49	93.3 5.11 20 2.49	92 6.38 20.3 2.49	16.6 8.51 20 0.995	34.1	93.1 10.2 20.7 2.99	18.7	93.1 8.09 28.6 2.49	9.36 29.1	35.3 29.1	10.2 85	80.
	1.90	1.49	4.40	2.49	09.7	00.2	1.99	2.49	2.49	2.49	47.5	2.49	0.990	60.0	2.99	2.99	2.49	60.0	4.00	70.1	0.4

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