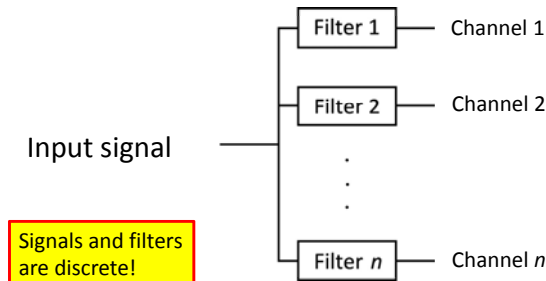


# Multi-dimensional Signal Analysis

Lecture 2G  
Filter Banks and  
Multi-resolution Analysis (I)

## Filter banks

- A common type of processing unit for discrete signals is a filter bank, where some input signal is filtered by  $n$  filters, producing  $n$  channels



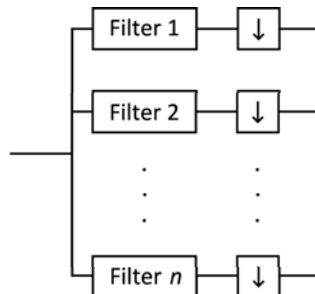
Signals and filters are discrete!

This an example of how to create  $n$  channels

## Filter banks

- In order to have the same amount of data (on average per time unit) before and after the filtering: down-sample the filter outputs by a factor  $n$

- Keep every  $n$ -th sample



## Filter banks, applications

- One application for filter banks is to decompose the input signal into different *bands* or *channels*
- Here *band* is rather imprecise and can mean frequency band but also more general subspaces

## Filter banks, applications

- Each band is processed independently relative to the others
  - Filtering, e.g., LP-filter to reduce noise
  - Data compression, to reduce data
  - Numerical resolution, to reduce data
  - Even: removal, to reduce data
- Each band is then stored or transmitted
- From each band we want to be able to reconstruct the input signal again
  - Possibly only to some degree of approximation
  - Or *perfect reconstruction*: output = input (+ shift!)

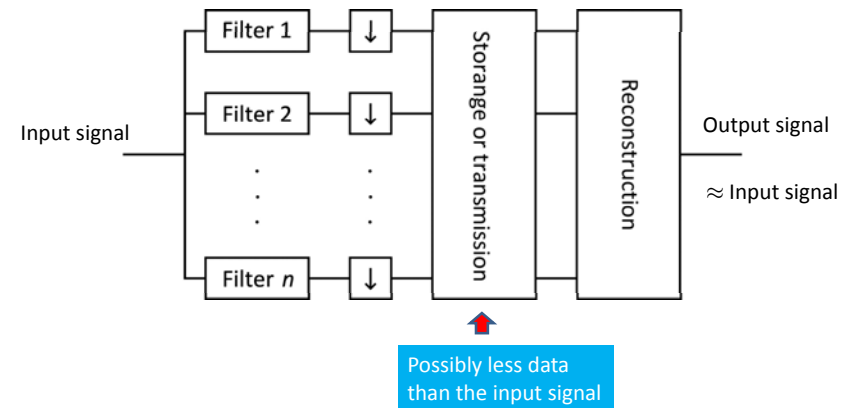
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## Filter banks, applications

- In general, something like this:



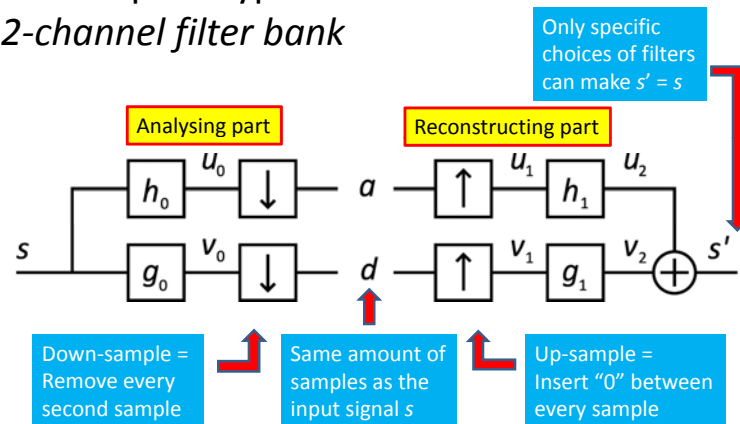
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## The 2-channel filter bank

- The simplest type of filter bank is the *2-channel filter bank*



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## The 2-channel filter bank

- Let the DFTs of  $h_0, h_1, g_0, g_1$  be denoted as  $H_0, H_1, G_0, G_1$  (they are  $2\pi$ -periodic!)
- We can show that necessary and sufficient conditions for  $s' = s$  are given by

$$H_1(u)H_0(u) + G_1(u)G_0(u) = 2 \quad (\text{FB1})$$

$$H_1(u)H_0(u + \pi) + G_1(u)G_0(u + \pi) = 0 \quad (\text{FB2})$$

- FB1: No distortion
- FB2: No aliasing from the sub-sampling (why?)

Ex 21.2

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## A practical note

Assuming that all four filters are causal:

- The filters introduce delays in the output signal  $s'$
- This means that, at best, we can accomplish  $s'[k] = s[k - d]$  for some positive integer  $d$
- We will ignore this practical matter for now and consider the requirement  $s'[k] = s[k]$

As a consequence, some filters may become *non-causal*

- Can be fixed by time-shift if they also are FIR
- Output will then be delayed accordingly
- We want the four filters to be FIR

## Finding the four filters

- Bad idea: choose two of the filters *arbitrarily* and solve the other two from FB1 and FB2  
(why?)
- Better idea: Apply some design principles for the four filters that produce useful filters  
– Many possibilities exists!

## A particular choice of filters

- FB2 is automatically satisfied if

$$H_0(u) = \overline{H_1(u)}$$

$$G_1(u) = e^{-iu} \overline{H_1(u + \pi)}$$

$$G_0(u) = e^{iu} H_1(u + \pi) = \overline{G_1(u)}$$

Called:  
Conjugate  
Mirror filters

- FB1 then becomes

$$|H_1(u)|^2 + |H_1(u + \pi)|^2 = 2 \quad (O)$$

Ex 21.4

## Alternating flip

- The conjugate mirror filter condition can also be formulated in the time domain as

$$h_0[k] = \overline{h_1[-k]}$$

$$g_1[k] = (-1)^{1-k} \overline{h_1[1-k]}$$

$$g_0[k] = (-1)^{k+1} h_1[k+1] = \overline{g_1[-k]}$$

Called:  
Alternating flip

Ex 21.5

## An orthogonal set

- We can show that the condition (O) implies that

$$\langle h_1[\cdot] | h_1[\cdot - 2m] \rangle = \delta[m]$$

- $h_1$  is always orthogonal to itself when shifted by multiples of 2 (unless  $m = 0$ )

Ex 21.8

## Convolution and linear combinations

- We have already seen that the convolution operation can be interpreted in terms of producing linear combinations

- Here:

$$u_2[k] = \sum_{n=-\infty}^{\infty} a[n] h_1[k - 2n]$$

- The signal  $u_2$  is a linear combination of shifted versions of  $h_1$ 
  - Shift by multiples of 2
  - We just saw that they form an ON-set!

## More orthogonality

- In the same way we can show that the conjugate mirror filter bank leads to

$$\langle g_1[\cdot] | g_1[\cdot - 2m] \rangle = \delta[m]$$

$$\langle g_1[\cdot] | h_1[\cdot - 2m] \rangle = 0$$

Ex 21.11

(why?)

## More orthogonality

- This means that also  $v_2[k]$  is formed as a linear combination of orthonormal discrete functions  $g_1[k - 2m]$  ←

These are functions of  $k$ , one for each  $m$

- Finally, it also means that the two orthogonal sets  $h_1[k - 2m]$  and  $g_1[k - 2m]$  are mutually orthogonal

These are functions of  $k$ , one for each  $m$

## Reconstruction

- The output signal from the filter bank,  $s' = s$ , is formed as the linear combination of two orthogonal sets of functions (an ON-basis)
- Means: the coefficients in this linear combination are the *coordinates* relative the reconstructing basis functions. These are
  - $a[m]$  for the basis functions  $h_1[k - 2m]$
  - $d[m]$  for the basis functions  $g_1[k - 2m]$

## Analysis

- In the filter bank,  $a[m]$  is formed as

$$\begin{aligned} a[m] &= (s * h_0)[2m] \\ &= \sum_{k=-\infty}^{\infty} s[k] h_0[2m - k] \\ &= \sum_{k=-\infty}^{\infty} s[k] \overline{h_1[k - 2m]} = \langle s[\cdot] | h_1[\cdot - 2m] \rangle \end{aligned}$$

## Analysis

- Similarly:  $d[m] = \langle s[\cdot] | g_1[\cdot - 2m] \rangle$
- This result is expected!
- We are analysing  $s[k]$  using an ON-basis
- The corresponding coordinates are then given as the scalar products between  $s[k]$  and the basis functions
  - They are their own duals!

## Orthogonal filter bank

- In summary: we choose  $H_1$  such that

$$|H_1(u)|^2 + |H_1(u + \pi)|^2 = 2$$

and then the other three filters such that

$$\begin{aligned} H_0(u) &= \overline{H_1(u)} \\ G_1(u) &= e^{-iu} \overline{H_1(u + \pi)} \\ G_0(u) &= e^{iu} H_1(u + \pi) = \overline{G_1(u)} \end{aligned}$$

- This produces an *orthogonal filter bank*

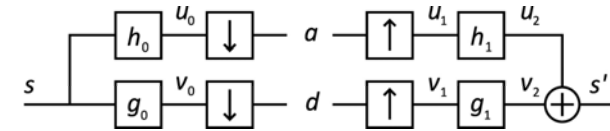
## Orthogonal filter bank

- If it is possible to choose  $h_1$  as a FIR filter, then  $h_0, g_1, g_0$  also become FIR
- Is this possible?
- Yes:  $h_1 = 2^{-1/2} (1, 1)$  is the simplest possible choice
  - $g_1 = 2^{-1/2} (-1, 1)$
  - $h_0 = 2^{-1/2} (1, 1)$
  - $g_0 = 2^{-1/2} (1, -1)$

Called:  
Haar filter bank

Other choices  
also exist!

## Splitting of the signal space



- The signal  $u_2$  is constructed as a linear combination of 2-shifts of  $h_1$ 
  - Span some subspace  $V_0$  of the signal space  $V$
- The signal  $v_2$  is constructed as a linear combination of 2-shifts of  $g_1$ 
  - Span some subspace  $W_0$  of the signal space  $V$
- The output signal  $s' \in V$  is  $u_2 + v_2$ 
  - $V = V_0 \oplus W_0, V_0 \perp W_0$

## Filter banks

- The conjugate mirror filter bank is only one special solution to FB1 and FB2!
- There are other ways of obtaining  $s' = s$ 
  - Still leads to perfect reconstruction
- Some approaches do not lead to an orthogonal filter bank
  - Can be useful anyway!

## Scaling function

Consider a function  $\phi(t)$  that satisfies

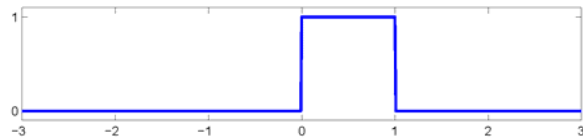
1.  $\phi(t - k), k \in \mathbb{Z}$ , is an orthogonal basis of some function space  $V_0$
2.  $\phi(t)$  can be written as a linear combination of the functions  $\phi(2t - k), k \in \mathbb{Z}$

- Such a function  $\phi$  is called a *scaling function*
- These relatively simple and innocent assumptions lead to a framework for defining a discrete wavelet transform in terms of orthogonal filter banks

## Example

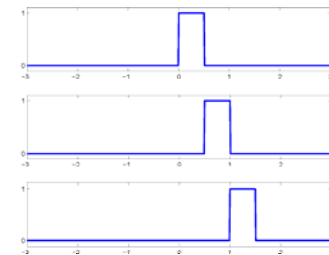
- The simplest example of a scaling function is

$$\phi(t) = \begin{cases} 1 & 0 \leq t < 1 \\ 0 & \text{otherwise} \end{cases}$$



## Example

- In this case:  $V_0$  is the space of **piece-wise constant functions** on integer intervals
- The functions  $\phi(2t - k)$  look like



$k = 0$

$k = 1$

$k = 2$

$$\phi(t) = \phi(2t) + \phi(2t - 1)$$

## Consequences

- The fact that  $\phi(t - k)$  is an orthogonal basis for  $k \in \mathbb{Z}$  means

$$\langle \phi(t) | \phi(t - k) \rangle = \int_{-\infty}^{\infty} \phi(t) \bar{\phi}(t - k) dt = \delta[k], \quad k \in \mathbb{Z}$$

- From this follows that also  $2^{1/2}\phi(2t - k)$ ,  $k \in \mathbb{Z}$ , form an orthogonal basis
  - Spans a function space  $V_1 \neq V_0$

Ex 22.1

Ex 22.2

## Consequences (II)

- Property 2. of the scaling functions leads to

$$\phi(t) = \sum_{k=-\infty}^{\infty} h_k 2^{1/2} \phi(2t - k)$$

for some sequence of scalars  $h_k$

Coordinates of  $\phi$  relative to the ON-basis  $2^{1/2}\phi(2t - k)$ ,  $k \in \mathbb{Z}$

- Since we have an ON-basis:

$$h_k = \langle \phi(t) | 2^{1/2} \phi(2t - k) \rangle = 2^{1/2} \int_{-\infty}^{\infty} \phi(t) \bar{\phi}(2t - k) dt$$

## Consequences (III)

- In fact, any  $\phi(x - l)$ ,  $l \in \mathbb{Z}$ , can be written as a linear combination of the basis  $2^{1/2}\phi(2t - k)$ :

$$\phi(t - l) = \sum_{m=-\infty}^{\infty} h_{m-2l} 2^{1/2} \phi(2t - m)$$

Ex 22.3

## Consequences (IV)

Notice that:

- The functions  $\phi(t - k)$  are shifted by multiples of "1" relative to  $t$ 
  - Spans a space denoted  $V_0$
- The functions  $2^{1/2}\phi(2t - k)$  are shifted by multiples of "1/2" relative to  $t$ 
  - Spans a space denoted  $V_1$
- Both bases are orthonormal within each space

Functions in  $V_1$  can contain finer details than  $V_0$

- $V_0 \subset V_1$

Since  $V_1$  has a basis that spans every basis vector in  $V_0$

## Consequences (V)

- Returning to property 1. we have seen that

$$\langle \phi(t) | \phi(t - k) \rangle = \delta[k]$$

- This can also be formulated as

$$\sum_k |\Phi(v + 2\pi k)|^2 = 1$$

Ex 22.4

where  $\Phi$  is the Fourier transform of  $\phi$

## The sequence $h$

- The sequence of scalars  $h[k]$ ,  $k \in \mathbb{Z}$ , depends *only* on the choice of scaling function  $\phi$
- Remember that  $\phi$  itself has particular properties, described by 1. and 2.
  - Also  $h[k]$  has particular properties!
- $h[k]$  can be interpreted as the coefficients of a discrete filter with Fourier transform

$$H(u) = \sum_{k=-\infty}^{\infty} h_k e^{-iuk}$$

This is a  $2\pi$ -periodic function



## The function $H$

- From 1. and 2. follows that  $H$  must be related to  $\Phi$  as

$$\Phi(u) = 2^{-1/2} H\left(\frac{u}{2}\right) \Phi\left(\frac{u}{2}\right)$$

Ex 22.5

or

$$H(u) = 2^{1/2} \frac{\Phi(u)}{\Phi(2u)}$$

This must be a  $2\pi$ -periodic function!

## The function $H$

- The fact that  $\phi$  has special properties and that  $H$  is related to  $\phi$  leads to

$$|H(u)|^2 + |H(u + \pi)|^2 = 2$$

Ex 22.6

- We recognise this as condition (O) on the filter  $h_1$  in a conjugate mirror filter bank!

## The function $\psi(x)$

- Define a new function  $\psi(t)$ , with a Fourier transform  $\Psi$  given by

$$\Psi(u) = \frac{1}{\sqrt{2}} G\left(\frac{u}{2}\right) \Phi\left(\frac{u}{2}\right)$$

Where

$$G(u) = e^{-iu} \overline{H(u + \pi)}$$

This is the alternating flip condition in a conjugate mirror filter bank

or

$$g[n] = (-1)^{1-n} h[1 - n]$$

## The sequence $g$

- The sequence  $g$  is derived from  $h$
- But,  $h$  depends only on  $\phi$ :
  - $g$  depends only on  $\phi$
- Also  $\psi$  depends only on the choice of  $\phi$
- Finally, we can derive

$$\langle \psi(t) | 2^{1/2} \phi(2t - n) \rangle = g[n]$$

Ex 22.7

## The sequences $h$ and $g$

We summarise:

$$h[k] = \langle \phi(t) | 2^{1/2} \phi(2t - k) \rangle$$

Coordinates of  $\phi$   
relative basis in  $V_1$

$$g[k] = \langle \psi(t) | 2^{1/2} \phi(2t - k) \rangle$$

Coordinates of  $\psi$   
relative basis in  $V_1$

or, more generally:

$$\langle \phi(t - l) | 2^{1/2} \phi(2t - k) \rangle = h[k - 2l]$$

At least if we  
can prove that  
 $\psi \in V_1$

$$\langle \psi(t - l) | 2^{1/2} \phi(2t - k) \rangle = g[k - 2l]$$

## Properties of $\psi$ , (I)

• We can show that:

Ex 22.8

$$\psi(t - l) = \sum_k (-1)^k \overline{h_k} 2^{1/2} \phi(2t - k + 2l + 1)$$

which means that all  $\psi(t - l) \in V_1, l \in \mathbb{Z}$

$\Rightarrow g_n$  are the coordinates of  $\psi$  in the ON-basis of  $V_1$

## Example

• For the simple example of a scaling function

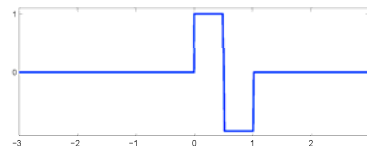
$$\phi(t) = \begin{cases} 1 & 0 \leq t < 1 \\ 0 & \text{otherwise} \end{cases}$$

we get

$$g[k] = \{2^{-1/2}, -2^{-1/2}\}$$

Called Haar wavelet

and the  
corresponding  
function  $\psi(t)$ :



## Properties of $\psi$ , (II)

• Using the previous relations, we can also prove that

Ex 22.9

$$\langle \psi(t - m) | \phi(t - l) \rangle = 0 \quad \text{for } l, m \in \mathbb{Z}$$

which means that all  $\psi(t - l)$  are orthogonal to the space  $V_0$  since  $\phi(t - m)$  is a basis for this space

•  $\psi(t - m) \in V_1$  and  $\psi(t - m) \perp V_0$

## Properties of $\psi$ , (III)

- We can also show that

$$\langle \psi(t-n) | \psi(t) \rangle = \delta[n]$$

Ex 22.10

(why?)

which means that the set  $\psi(t-n)$  is orthonormal for  $n \in \mathbb{Z}$

- In summary:
  - All  $\psi(t-n)$  are  $\perp$  to  $V_0$
  - They form an orthonormal set

## Properties of $V_1$

- Let  $f$  be an arbitrary function in  $V_1$ . It can then be written as

$$f(t) = \sum_n s[n] 2^{1/2} \phi(2t-n)$$

for some sequence  $s[n]$  since  $2^{1/2}\phi(2t-n)$  is an ON-basis for  $V_1$

## Properties of $V_1$

- Using the previous results, we can show that it is also possible to write this  $f \in V_1$  as

$$f(t) = \sum_n a[n] \phi(t-n) + \sum_n d[n] \psi(t-n)$$

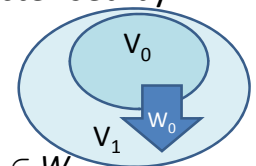
Ex 22.11

for some sequences  $a[k]$  and  $d[k]$

- This means that  $\phi(t-n)$  and  $\psi(t-n)$  together span  $V_1$

## The difference space $W_0$

- $V_0$  is a subspace of  $V_1$
- Any  $f \in V_1$  can be written as a unique linear combination of a component in  $V_0$  and a component in  $V_1$ , and this component is orthogonal to  $V_0$
- There is a *difference space*  $W_0$  characterised by
  - $W_0 \subset V_1$
  - $W_0 \perp V_0$
  - $V_1 = V_0 \oplus W_0$
  - For any  $f \in V_1 : f = f_0 + w_0, f_0 \in V_0, w_0 \in W_0$



## The difference space $W_0$

- $V_1$  has an ON-basis  $2^{1/2} \phi(2t - k), k \in \mathbb{Z}$
- $V_0$  has an ON-basis  $\phi(t - k), k \in \mathbb{Z}$
- $W_0$  has an ON-basis  $\psi(t - k), k \in \mathbb{Z}$
  
- $W_0 \perp V_0$
- $V_1 = V_0 \oplus W_0$
  
- Coordinates of  $f \in V_1$  are given by  $s[k]$
- Coordinates of  $f \in V_0 \oplus W_0$  given by  $a[k]$  and  $d[k]$

## Sequences $a, b$ and $c$

- Since  $f \in V_1$  is completely represented either by sequence  $s[k]$ , or by sequences  $a[k]$  and  $d[k]$  :
  - There must be a (linear) mapping  $s \rightarrow (a, d)$
  - There must be a (linear) mapping  $(a, d) \rightarrow s$

## A linear mapping $a \rightarrow b \& c$

From previous results follows:

Ex 22.12

$$a[k] = (s[\cdot] * \overline{h[-\cdot]})[2k]$$

$$d[k] = (s[\cdot] * \overline{g[-\cdot]})[2k]$$

Convolve and skip every second sample (the odd ones)

## A linear mapping $b \& c \rightarrow a$

From previous results also follows:

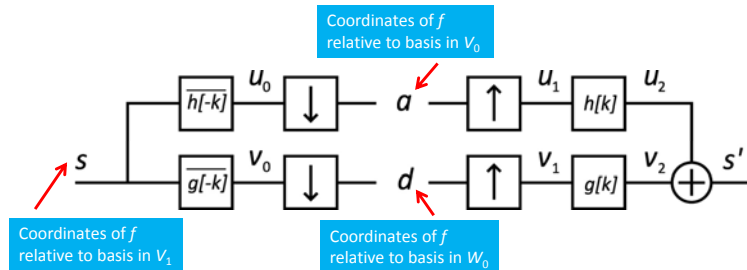
Ex 22.13

$$s[k] = \sum_{n=-\infty}^{\infty} (a[n] h[k - 2n] + d[n] g[k - 2n])$$

Insert zeros between every sample and convolve

## A 2-channel filter bank

- We can summarise these results as



An orthogonal 2-channel filter bank with

- $h_0 = h$
- $g_0 = g$  (as alternating flip of  $h_0$ )

## What you should know

- The anatomy of the 2-channel filter bank
- The 2 constraints on the 4 filters to produce  $s'=s$
- The conjugate mirror filter (CMF) bank
- Orthogonal 2-channel filter bank
- How a CMF decomposes the signal space into  $V_0$  and  $W_0$ , and how they are related
- Definition of a scaling function  $\phi$
- Leads to a unique function  $\psi$
- How  $\phi$  and  $\psi$  decompose the signal space into  $V_0$  and  $W_0$ , and how they are related