

Robot Vision Systems

Lecture 6: Rapid prototyping in OpenCV using Python and Ceemple

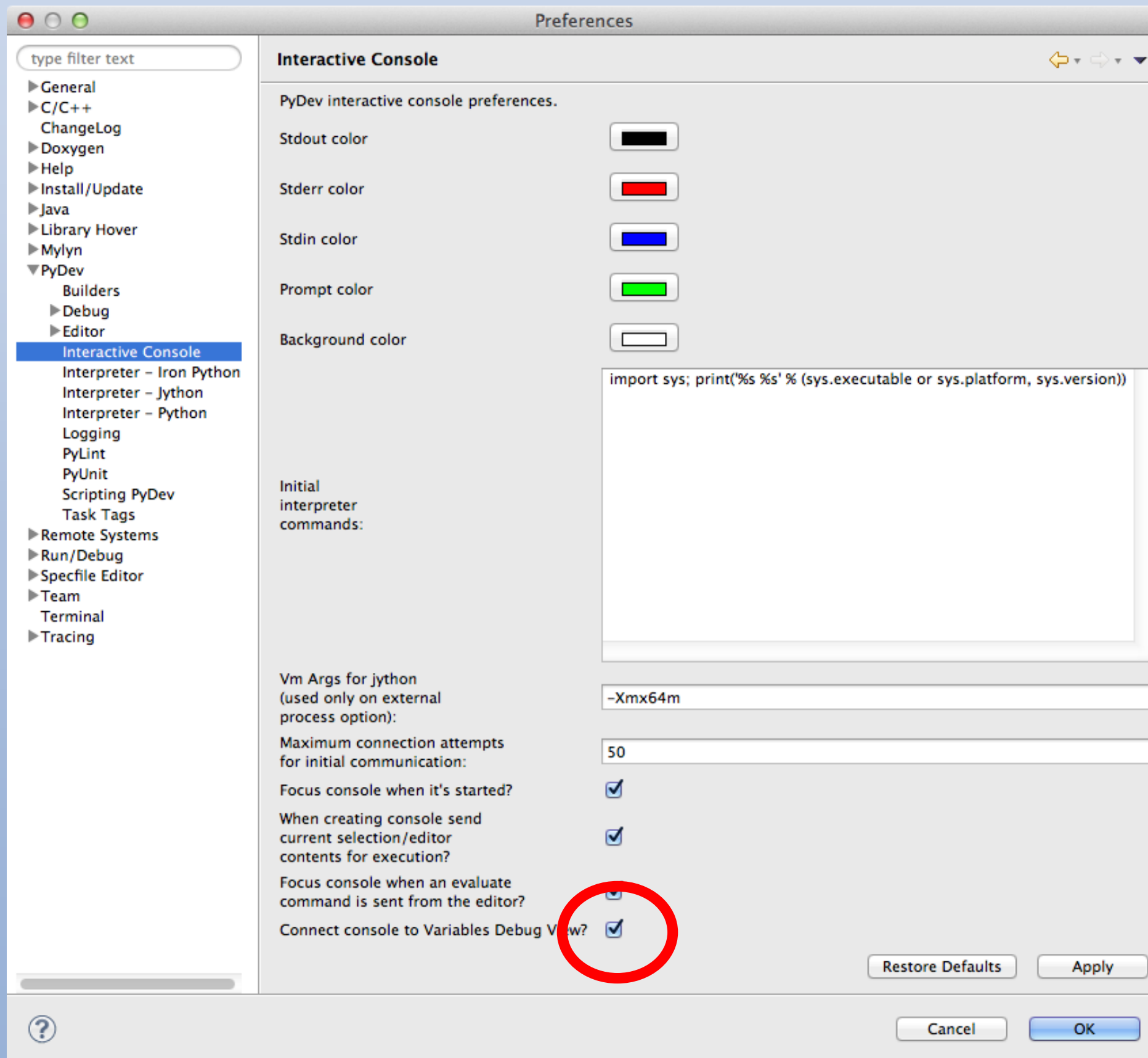
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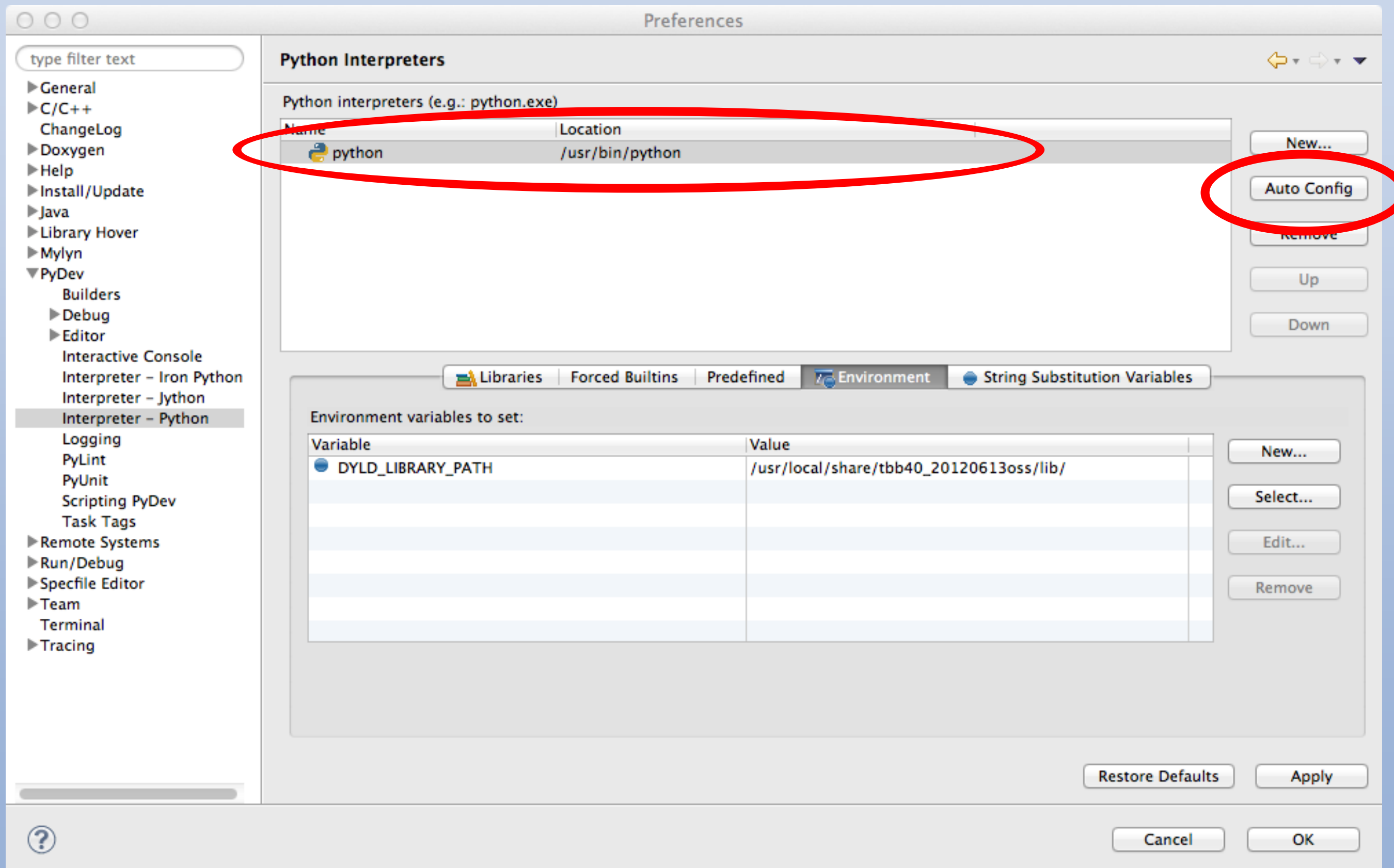
Python

- General purpose programming language
- Interpreted high-level language
- Readability: clear and expressive syntax
- Large standard library
- Multiple programming paradigms, a.o. OO
- Reference implementation CPython free and open source
- Version 3 can be used with OpenCV 3
- Integrated in Eclipse by means of **PyDev**

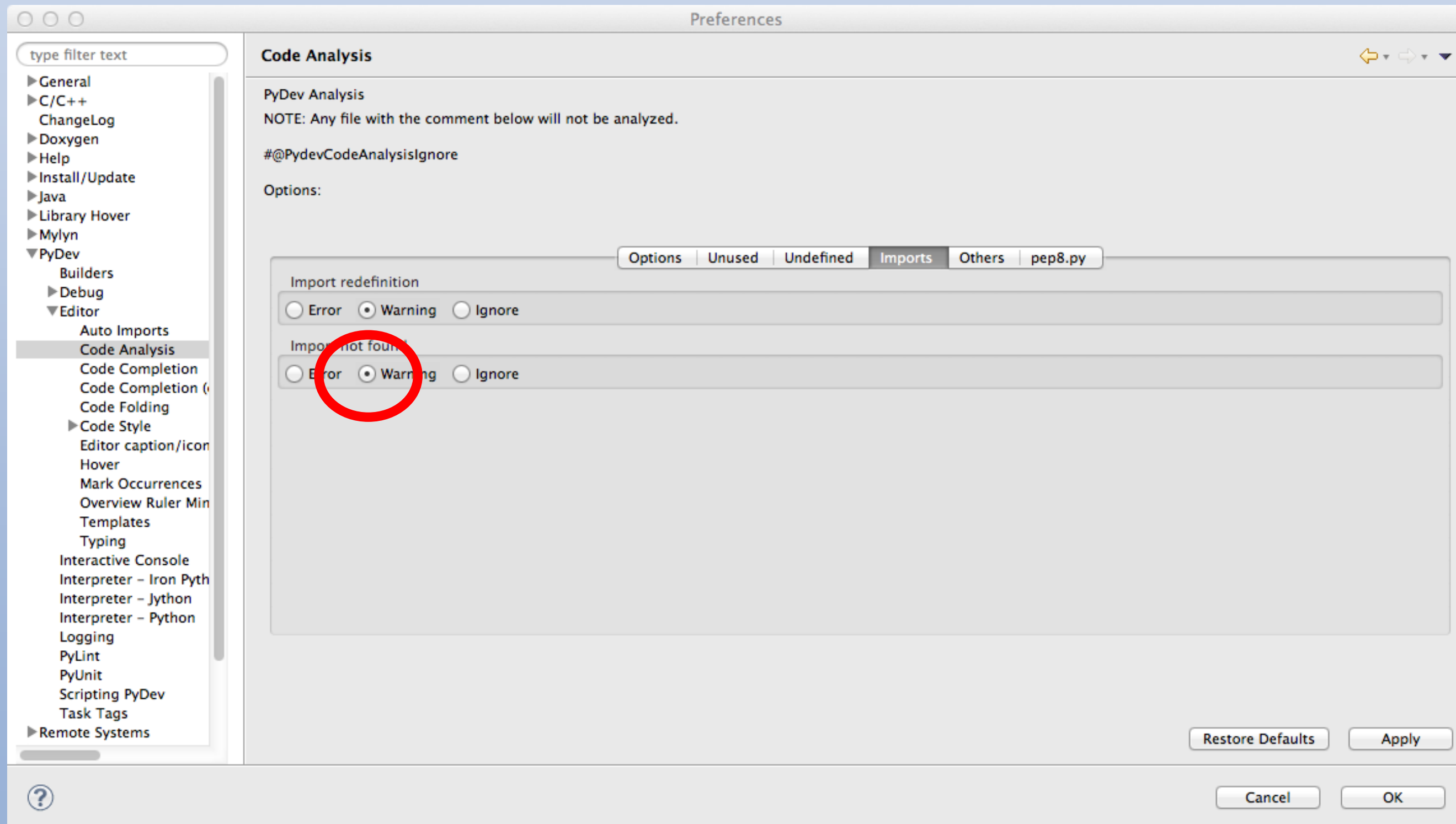
Interactive Workspace



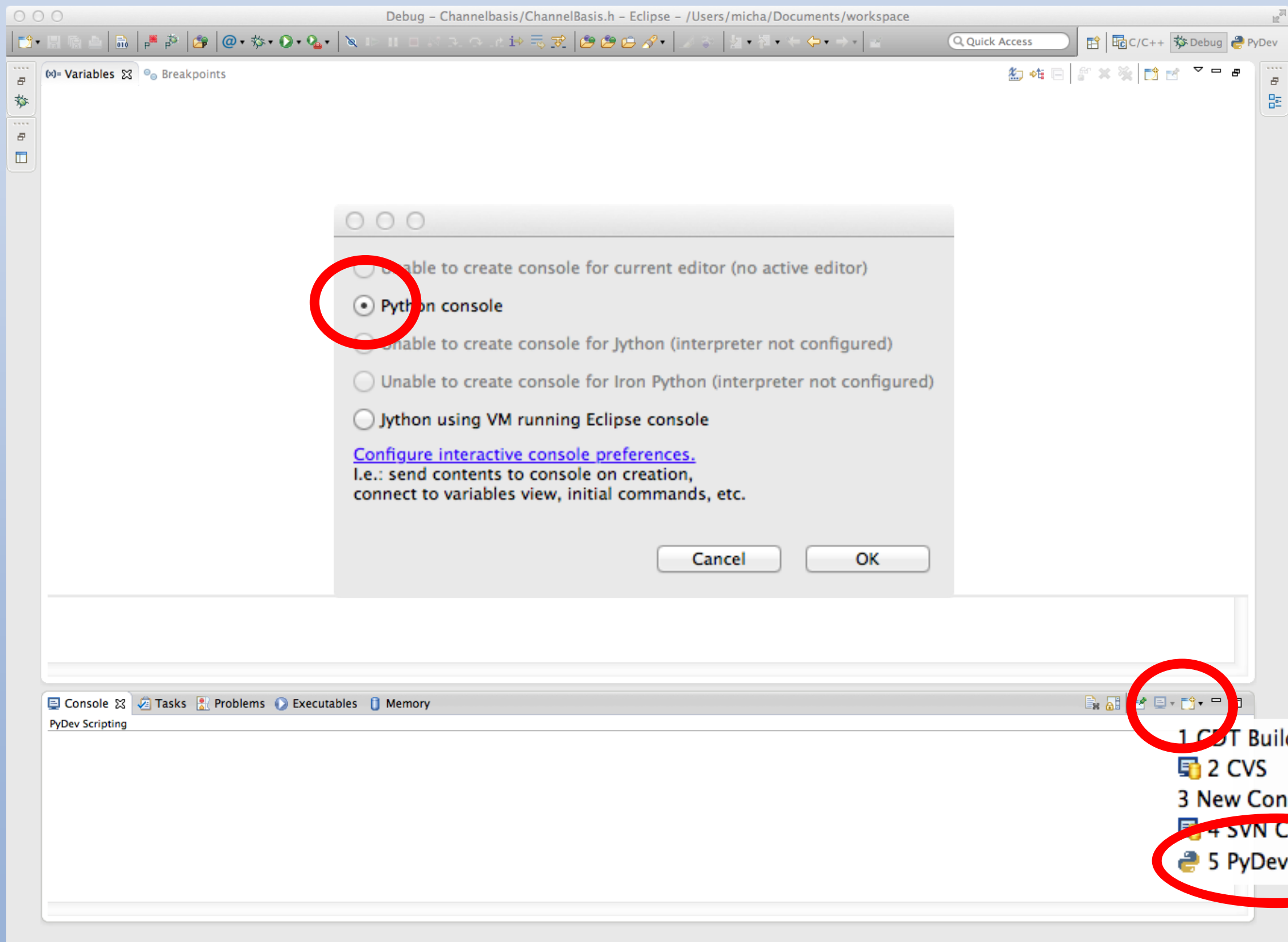
Interactive Workspace



Interactive Workspace



Open Console



Import NumPy

Debug - Eclipse - /Users/micha/Documents/workspace

Quick Access

C/C++ Debug PyDev

Variables Breakpoints

Name	Value
Globals	Global variables
ALLOW_THREADS	int: 1
BUFSIZE	int: 8192
CLIP	int: 0
ComplexWarning	type: <class 'numpy.core.numeric.ComplexWarning'>
DataSource	type: <class 'numpy.lib._datasource.DataSource'>
ERR_CALL	int: 3
ERR_DEFAULT	int: 0
ERR_DEFAULT2	int: 521
ERR_IGNORE	int: 0
ERR_LOG	int: 5
ERR_PRINT	int: 4
ERR_RAISE	int: 2
ERR_WARN	int: 1
FLOATING_POINT_SUPPORT	int: 1
FPE_DIVIDEZERO	int: 1
FPE_INVALID	int: 8
FPE_OVERFLOW	int: 2
FPE_UNDERFLOW	int: 4
False_	bool_: False
In	list: []
Inf	float: inf
Infinity	float: inf
MAXDIMS	int: 32
MachAr	type: <class 'numpy.core.machar.MachAr'>
NAN	float: nan
NINF	float: -inf
NZERO	float: -0.0
NaN	float: nan
Out	dict: {}

Console Tasks Problems Executables Memory

PyDev Console [1]

```
>>> import sys; print('%s %s' % (sys.executable or sys.platform, sys.version))
/Library/Frameworks/Python.framework/Versions/2.7/Resources/Python.app/Contents/MacOS/Python 2.7.3 (v2.7.3:70274d53c1dd, Apr 9 2012, 20:52:43)
[GCC 4.2.1 (Apple Inc. build 5666) (dot 3)]
PyDev console: using IPython 0.11
>>> from numpy import *
>>>
```

NumPy

- Python extension
- Multi-dimensional arrays
- High-level functions
- Similar to MATLAB, but more modern
- Also based on LAPACK
- Further extensions by means of SciPy and Matplotlib (native SVG support!)
- **OpenCV Mat are wrapped to NumPy arrays**

Example

- `x = linspace(0,2*pi,100)`
- `y = sin(x)`
- Better use 'import numpy' and explicitly writing `numpy.sin(x)` etc
- Result can be plotted:
 - `from matplotlib import pyplot`
 - `pyplot.plot(x, y)`
 - `pyplot.show()`

Using OpenCV in Python

- OpenCV functions are in Python module cv2
 - import cv2
- OpenCV1 is no longer supported
- Use autoexpand in Eclipse and search in documentation to find function names
- Problem with Ceemle: missing Python bindings
 - Install Python: WinPython (Windows) or via apt-get
 - Download OpenCV 3 (binary (Windows) or build (*), see <http://milq.github.io/install-opencv-ubuntu-debian/>)
 - Copy cv2.pyd to Lib\site-packages (Windows) or cv2.so to /usr/local/lib/python2.7/site-packages
 - (*) experimental: copy first /opt/ceemle/lib/* to build/lib/ before running “make opencv_python2”

Example: Read from Cam

- `capture = cv2.VideoCapture(0)`
- `[status,img] = capture.retrieve()`
- `cv2.imshow("camera",img)`
- `cv2.waitKey(0)`
- `cv2.destroyAllWindows()`
- Note that *status* contains binary flag
- Without `waitKey(0)`, window will not be created (0 means: infinitely long)

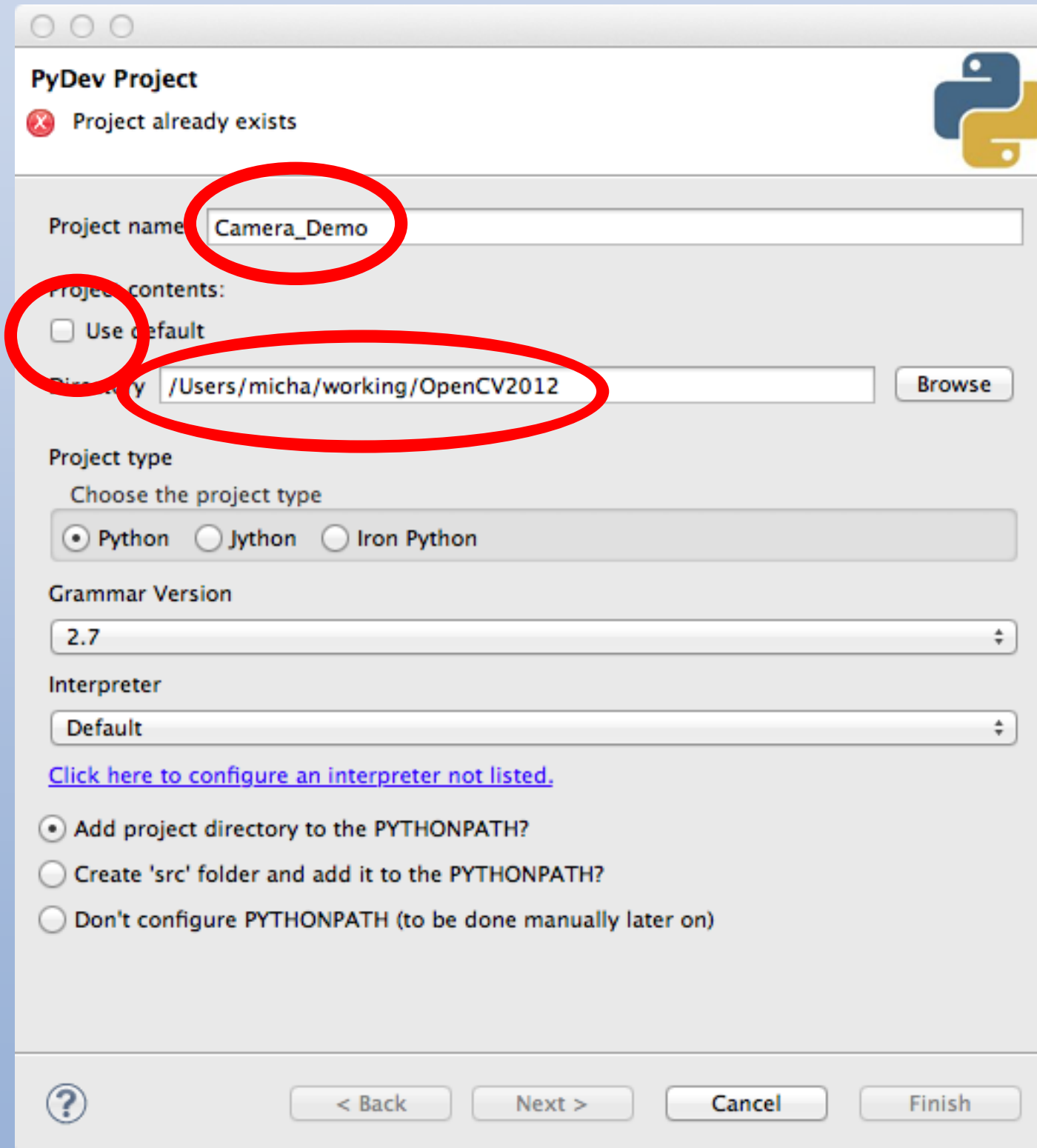
Example: Color Edges

- `h2 = numpy.array([[-1.0, 0 , 1]]).T.dot(
 numpy.array([[1, 2, 1]]))`
- `edgex = cv2.filter2D(img, cv2.CV_32F, h2.T)`
- `edgey = cv2.filter2D(img, cv2.CV_32F, h2)`
- `mag = cv2.magnitude(edgex, edgey)`
- `cv2.imshow("camera",
 cv2.convertScaleAbs((255.0/mag.max())*mag))`
- `cv2.waitKey(0)`
- `cv2.destroyAllWindows()`
- Note that *magnitude* only works with floats

Generating Scripts

- As in MATLAB: just pipe your command line commands into a text-file
- Suffix: .py
- You may run the script from command-line by `python my_script.py`

Generating Projects



PyDev Project

Project already exists

Project name: Camera_Demo

Project contents:

☐ Use default

Directory: /Users/micha/working/OpenCV2012 Browse

Project type

Choose the project type

☒ Python ☐ Jython ☐ Iron Python

Grammar Version

2.7

Interpreter

Default

[Click here to configure an interpreter not listed.](#)

☒ Add project directory to the PYTHONPATH?

☐ Create 'src' folder and add it to the PYTHONPATH?

☐ Don't configure PYTHONPATH (to be done manually later on)

? < Back Next > Cancel Finish

Package and Modules

- A PyDev project is just a container for packages
- Packages correspond (in a certain way) to C++ namespaces and are containers for modules
 - Next step: generate package
- Modules correspond to .cpp files and are containers for functions and scripts
 - Next step: generate module ('main') and add code

Prototyping in Ceemple

- No interactive console (drawback or advantage?)
- Only on Windows (drawback)
- Same syntax (advantage)
- Matplotlib is not available (drawback)
- Weak support for debugging of Mat (drawback)
- Not all math available (drawback)
- Faster execution (advantage)
- No extra testing needed (advantage)